

### Large Area High Temperature Copper Pillar Probing



Gunther Boehm Daniel Malitius Antonela Marić

June 2-5,2019

Why Large Area? Why High Temperature? Trends for Copper Pillar Probing

probing temperature

#### area, total force





if you just heat up the prober...



result of an alignment issue: offset probing, deep impact

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Basics of

### Large Area High Temperature Copper Pillar Probing



• Alignment:

- good needle to needle alignment
- matching CTE of guide plates
- overtravel:
  - coplanarity wafer to probe card
     system deflection under control

small Cu-pillar deformation @ elevated temperature

low resistance contact mechanism

# History of SWTW Presentations

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![](_page_3_Figure_1.jpeg)

System deflection

Copper pillar

![](_page_3_Figure_4.jpeg)

![](_page_4_Picture_0.jpeg)

- Introduction: Copper pillar, high temperature, high pin count
- Guide plate CTE improvement
- System (test cell) deflection @ high pin count
- Copper pillar contact @ 150°C probing temperature
- Summary

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## Guide plate CTE improvement

### Coefficient of Linear Thermal Expansion (α)

- Characterizes the materials change of size in response to a change in temperature ( $\Delta T$ ).
  - (Eg.: Thermometer)
- While heating, the average kinetic energy increases  $\rightarrow$  the volume/length increases:

$$L_T = L_0 \cdot e^{\alpha \cdot \Delta T}$$

(Taylor series)

$$L_T = L_0 + \Delta L \approx L_0 + \alpha \cdot L_0 \cdot \Delta$$

 $\alpha = \frac{1}{L_0} \frac{\Delta L}{\Delta T}$ 

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![](_page_5_Picture_10.jpeg)

Expansion joint on a road bridge

# Guide plate CTE improvement

#### Coefficient of Thermal Expansion (α) of a Probe Card

![](_page_6_Figure_2.jpeg)

![](_page_6_Figure_3.jpeg)

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### Guide plate CTE improvement Guide plate CTE vs. System CTE

### • Guide Plate (Material) CTE

Material characteristics

 $\alpha = \frac{1}{L_0} \frac{\Delta L}{\Delta T}$ 

Measurement: optical dilatometer

### System CTE

- Characterizes the situation in a real probing environment
  - The probe head never reaches the prober's chuck temperature
- Measurement: real probing environment

![](_page_7_Figure_9.jpeg)

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# Guide plate CTE improvement CTE Verification Method I/II

#### Measurement Method

- Real probe head (45x45 mm<sup>2</sup> max image size), 14 diagonals measured
- UF3000 probing on a blanc wafer @:
  - -40°C +28°C +85°C +150°C +180°C

### • Experiment Design:

- 2 systems (high/low pin count)
- 5 probing temperatures
- 3 touchdowns per temperature
- 2 measurements per touchdown14 distances per measurement

200mm blanc Al-wafer, 3 touchdowns

3

Probe head used for measurements

0

(0)

0

0

 $\bigcirc$ 

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### Guide plate CTE improvement CTE Verification Method II/II

### The Measurement of the Scrubmarks:

- Coordinate measurement of the scrub position at 20°C
- Calculating the length for each probing temperature:

 $\alpha$  of the silicon wafer

– Calculating the CTE of the System:

$$\alpha = \frac{\ln\left(\frac{1}{L_0}\right)}{\Delta T}$$

 $(L_{T})$ 

 $L_T = L_0 \cdot e^{\alpha \cdot \Delta T}$ 

– Calculating the mismatch:

![](_page_9_Figure_8.jpeg)

Position mismatch needle to Cu-pillar

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### Guide plate CTE improvement Measurement Setup

### • "WERTH IP400" Coordinate Measurement System

accuracy:  $E_2 = 1,15 \mu m + \frac{L}{400} m \cdot mm^{-1}$ 

![](_page_10_Picture_3.jpeg)

![](_page_10_Picture_4.jpeg)

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Guide plate CTE improvement

**Results** 

• Guide Plate CTE

![](_page_11_Picture_3.jpeg)

### System CTE ≠ System II CTE

The system\* CTE depends on the needle count!

\* System 1: 3.380 needles, System 2: 54 needles

![](_page_11_Figure_7.jpeg)

### Guide plate CTE improvement **Mismatch vs. Temperature**

The mismatch (x) describes how the needle tip changes its position on the pad with a change in temperature.

depends on the system CTE and the temperature

![](_page_12_Figure_3.jpeg)

![](_page_12_Figure_5.jpeg)

### Guide plate CTE improvement Summary CTE

- We have developed an experimental method to measure the system CTE in the real environment.
- By understanding the physics of the system, we defined the material with  $\overline{\phantom{a}}$ the best matching CTE.
- With the new material we optimized the system and minimized the  $\mathbf{O}$ mismatch from 13,4  $\mu$ m to 1,8  $\mu$ m @180°C for a 100x100 mm<sup>2</sup> image size.

![](_page_13_Figure_4.jpeg)

![](_page_14_Picture_0.jpeg)

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### System Deflection **System Deflection Overview**

#### deflection mechanism

### influence to the contact force

![](_page_15_Figure_3.jpeg)

![](_page_15_Figure_5.jpeg)

force vs overtravel for ViProbe® T-type

#### reasons for system deflection:

- headplate bending
- chuck deflection and tilt
- probe card bending
- tester interface bending
- temperature effects
- (... but that's a story on it's own)

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### What is your system deflection?

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overtravel

overtravel

# System Deflection Experiment Objective

To determine the system deflection for a

- space transformer probe card with 7360 ViProbe T-type needles (equivalent to 257N = 25,7kgf of contact force @ 100μm overtravel)
- on an Accretech UF3000 EX prober (300mm)
- with a J750 tester

![](_page_16_Picture_5.jpeg)

"system" = probe card + prober + tester

side condition:

- ambient temperature (to be able to distinguish between force- and temperature effects)

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![](_page_17_Figure_0.jpeg)

a gold wafer has been choosen to avoid errors from the contact resistance

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needle height range:

-20µm up to +110µm

# System Deflection Experiment Setup

#### • Needle Height Distribution

needle heights have been manually measured using a microscope

(measurement using a probe card analyzer failed due to insufficient range at optical measurement)

![](_page_18_Figure_4.jpeg)

# System Deflection Experiment Setup

### Experiment Parameter

- Six different touchdown positions
- Special test program: resistance test only
- current: 10µA
- Threshold for "contact": 1000  $\Omega$
- Manual overtravel control
- All sites, not only the selected sites, have been included into the measurement to have a bunch of contacts that represent the "zero" height

![](_page_19_Figure_8.jpeg)

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south overlap

# System Deflection Measurement Data

Center Position

#### To get 100µm AOT a POT of **160µm** is required.

POT =  $\underline{\mathbf{p}}$ rogrammed  $\underline{\mathbf{o}}$ ver $\underline{\mathbf{t}}$ ravel AOT =  $\underline{\mathbf{a}}$ ctual  $\underline{\mathbf{o}}$ ver $\underline{\mathbf{t}}$ ravel

A data point in the diagram means:

- it's X-value is the relative prober Z-stage height when this needle had first contact to the wafer
- it's Y-value is the previously measured relative needle height

![](_page_20_Figure_7.jpeg)

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# System Deflection Measurement Data

### South Position

To get 100μm AOT a POT of **165-180μm** is required. A **tilt** is clearly visible.

POT =  $\underline{\mathbf{p}}$ rogrammed  $\underline{\mathbf{o}}$ ver $\underline{\mathbf{t}}$ ravel AOT =  $\underline{\mathbf{a}}$ ctual  $\underline{\mathbf{o}}$ ver $\underline{\mathbf{t}}$ ravel

A data point in the diagram means:

- it's X-value is the relative prober Z-stage height when this needle had first contact to the wafer
- it's Y-value is the previously measured relative needle height

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![](_page_21_Figure_8.jpeg)

### System Deflection Measurement Data

 South Overlap Position

> To get 100μm AOT a POT of **155μm** is required. 50% of the force reduces the deflection only gradually.

POT =  $\underline{\mathbf{p}}$ rogrammed  $\underline{\mathbf{o}}$ ver $\underline{\mathbf{t}}$ ravel AOT =  $\underline{\mathbf{a}}$ ctual  $\underline{\mathbf{o}}$ ver $\underline{\mathbf{t}}$ ravel

A data point in the diagram means:

- it's X-value is the relative prober Z-stage height when this needle had first contact to the wafer
- it's Y-value is the previously measured relative needle height

![](_page_22_Figure_7.jpeg)

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# System Deflection System Deflection

- System deflection has been measured for 257N (25,7kgf) contact force
- System deflection (POT minus AOT) is 60µm in the chuck center for 160µm POT
- At the wafer edge the system deflection can rise up to 85µm due to tilt of components
- System characterization is essential to get your high pin count probing process under control

![](_page_23_Figure_5.jpeg)

![](_page_23_Figure_7.jpeg)

![](_page_23_Figure_8.jpeg)

![](_page_23_Figure_9.jpeg)

![](_page_23_Figure_10.jpeg)

![](_page_24_Picture_0.jpeg)

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#### Cu Pillar Contact Cu Pillar Contact Cu Pillar Contact at 150°C Probing Temperature

• Pictures from 150°C Cu Pillar Probing Trials

![](_page_25_Picture_2.jpeg)

position offset

deep impact, fissure

large deformation

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**FEASIBLE?** 

Ô

### **Cu Pillar Contact** Material characteristic of the used Cu pillar

![](_page_26_Figure_1.jpeg)

Sn-Ag-Cu lead-free solder"; Journal of Electronic Materials 39(2):223-229 February 2010 SWTest | June 2-5,2019

### Cu Pillar Contact Challenges at 150°C test temperature

#### • Requirements

- Stable contact resistance
- Small bump deformation
- Similar bump height after probing

### Adjustable parameter

- Overtravel
- Contact force
- Contact surface

![](_page_27_Picture_9.jpeg)

### Soft mechanical contact with good contact resistance!

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### **Style / Format Guidelines**

### Experiment Setup

- MµProbe<sup>®</sup> M-Type
  - Contact force
  - Cleaning material 3M pink (3μm)
- MµProbe<sup>®</sup> N-Type
  - Contact force
  - Cleaning material

![](_page_28_Picture_8.jpeg)

3.8cN

SnAg

85µm

0.05g

- Cu pillar with solder cap
  - Solder material
  - Bump height
  - Bump diameter 100μm
- Accretech UF3000
  - Voltage|Current 2V|20mA
  - Prober acceleration
  - Prober velocity 18000µm/s

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![](_page_28_Figure_19.jpeg)

### Cu Pillar Contact Measurement Data

### • Influence of the Overtravel

![](_page_29_Figure_2.jpeg)

More overtravel shows almost no difference

![](_page_29_Figure_4.jpeg)

Correlation between Cres and overtravel @ high temperature only

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### Cu Pillar Contact Measurement Data

### • Influence of the Contact Force

![](_page_30_Figure_2.jpeg)

A higher contact force leads to more deformation, especially at high temperature

No correlation between bump deformation and Cres, the temperature matters

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# Cu Pillar Contact Measurement Data

### • Influence of the Contact Surface

#### MµProbe<sup>®</sup> M-Type

- Contact force 3,8cN
- Overtravel 100µm

![](_page_31_Picture_5.jpeg)

M-Type: standard

M-Type: rough surface

![](_page_31_Figure_8.jpeg)

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# Cu Pillar Contact Probe Card Data

#### • MµProbe<sup>®</sup> M/N-Type: Solution for 150°C Bump and Cu Pillar Probing

	N-Type	М-Туре
Full array pitch	80 µm	90 µm
Contact force	2,0 cN (gf)	3,8 cN (gf)
CCC @ 28°C	500 mA	717 mA
CCC @ 150°C	470 mA	667 mA

![](_page_32_Figure_3.jpeg)

M-Type head, wafer side view

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M-Type - Lifetime estimation due to cleaning Cleaning recipe: 1x3M - 50µm octagonal - 30µm OD 600 Very aggressive (every 100TDs) Aggressive (every 200TDs) extension testers 300 500 Pulling a shim -Soft (every 500TDs) 3 Mio TDs 6 Mio TDs 16 Mio TDs ₫ 100 0 5 Mio 0 Mio 10 Mio 15 Mio 20 Mio # Touchdowns

M-Type Lifetime Chart: "Shimming" leads to extended lifetime

➔ US pat. no.: US 7795888 B2

## Cu Pillar Contact Cu Pillar Contact Summary

### • Influence of Parameter Changes

![](_page_33_Picture_2.jpeg)

Higher contact force

 $\rightarrow$  increased bump deformation

More overtravel

 $\rightarrow$  Cres improvement @ 150°C

Rougher contact surface

 $\rightarrow$  better and more stable Cres

### $\rightarrow$ A rough surface is the key to low contact resistance!

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### Summary Necessary Basics of Large Area High Temperature Copper Pillar Probing

![](_page_34_Picture_1.jpeg)

- High CTE ceramic enables high temperature large area probing
- Knowing your AOT is essential to deal with high force | high pin count probe cards
- Probing SnAg Cu pillar @ 150°C is feasible. Online cleaning needs special attention.

### The Finish Presentation Highlights

![](_page_35_Picture_1.jpeg)

![](_page_35_Figure_2.jpeg)

![](_page_35_Figure_3.jpeg)

![](_page_35_Figure_4.jpeg)

![](_page_35_Figure_5.jpeg)

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**Prober operation** 

Experiment design

Special head assembly

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**Thank you!** 

Gunther Boehm Manager R&D FEINMETALL GmbH +49 (7032) 2001 - 149 E: gunther.boehm@feinmetall.de

Antonela Marić R&D Engineer FEINMETALL GmbH +49 (7032) 2001 - 353 E: antonela.maric@feinmetall.de

Daniel Malitius R&D Technician FEINMETALL GmbH +49 (7032) 2001 - 474 E: daniel.malitius@feinmetall.de

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