



SWTEST

PROBE TODAY, FOR TOMORROW

Smart Cars – Smart Probe Cards



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T.I.P.S. Messtechnik

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Overview

- ▷ **1. Introduction**
- ▷ **2. Smart Probe Cards**
 - ▷ 2.1 Illumination field module
 - ▷ 2.2 MEMS mirror module
- ▷ **3. Conclusion**
- ▷ **4. Acknowledgement**

1. Introduction

Ongoing evolution within individual car traffic

- **Further improvement of Advanced Driver Assistance Systems**
 - Compensation/avoidance of human errors that lead to accidents
 - Driver becoming more and more to passengers of **autonomous SMART CARS**
- **Smart cars need multiple sensors to evaluate the status quo:**
 - Driving condition: Speed, acceleration, steering angle, wheel specific slip, etc.
 - Environment: Obstacles, distance to other cars, course of driving lane, etc.
- **Recent sensor types need additional functional testing, conducted by SMART PROBE CARDS**

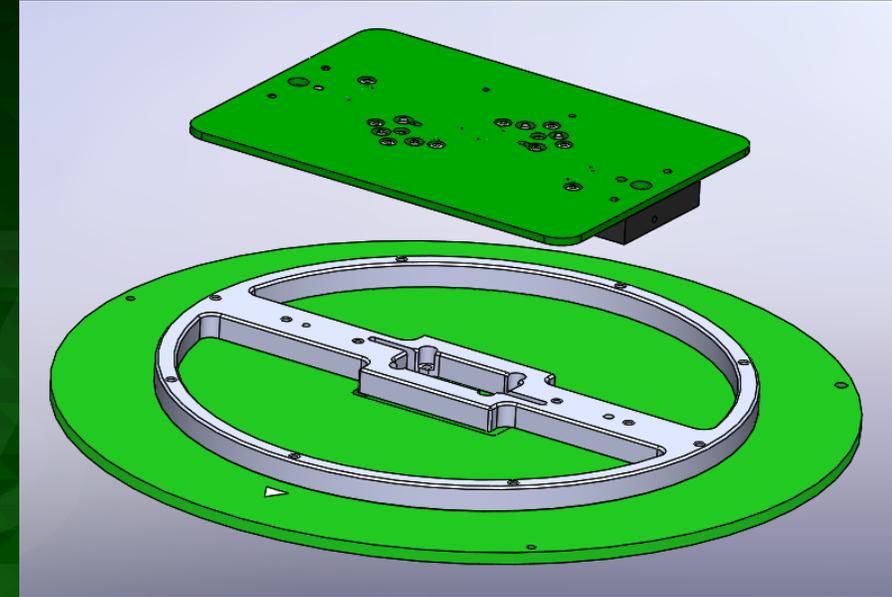


Source: Bluedrop

2. Smart probe cards

What are the challenges?

- **Additional functional testing besides electrical tests**
 - Stimulation of chip-integrated sensors
 - Examination of micromechanical actuators and sensors
- **Enhancement of standard probe cards by add-on modules to provide this ability**
- **This presentation shows selected developments for the integration of add-on modules for LiDAR Systems**



2. Smart Probe Cards

What is LiDAR?

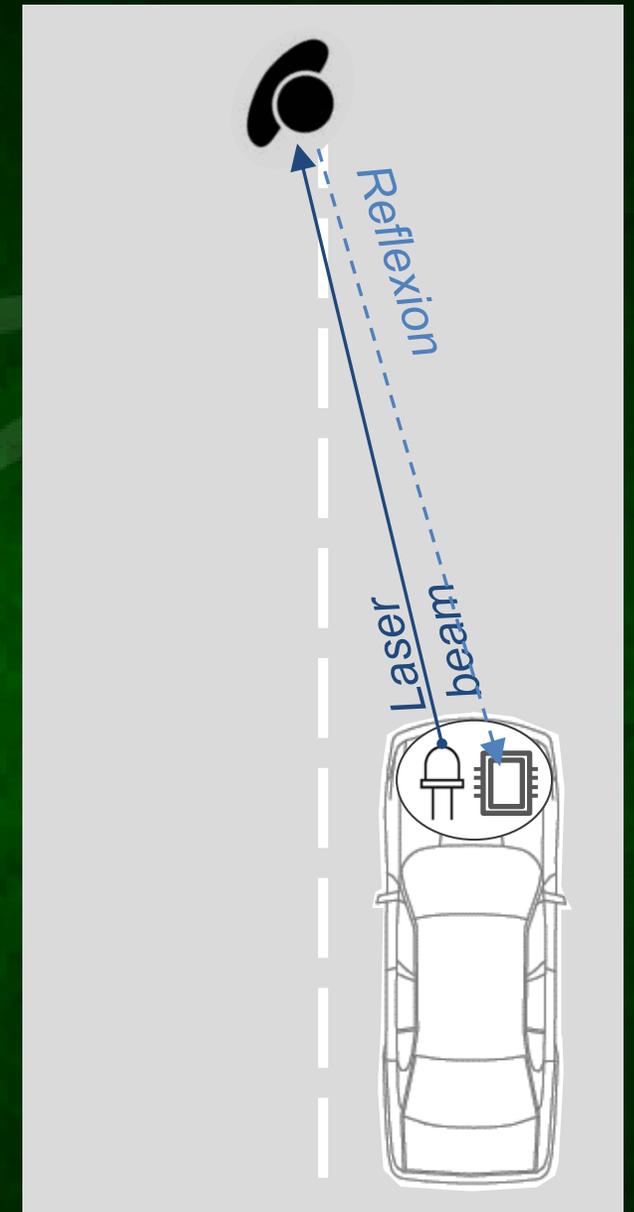
- **Light Detection And Ranging - LiDAR**

- System for optical distance measurement
- First used in atmospheric research and meteorology
- Key technology for autonomous driving

- **Determination of time-of-flight**

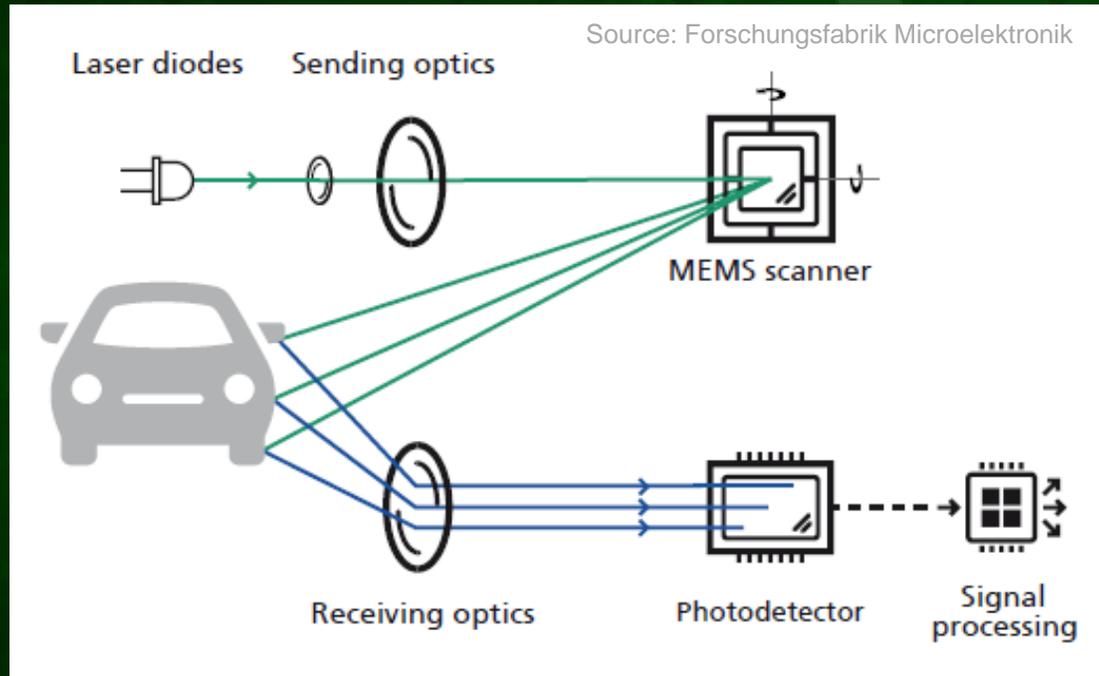
- Light is emitted by the laser source in changing directions
- This light is reflected by an object and then received by a detector
- Time delay Δt between emission and receiving determines distance

$$Distance = Speed_{Light} \cdot \frac{\Delta t}{2}$$



2. Smart Probe Cards

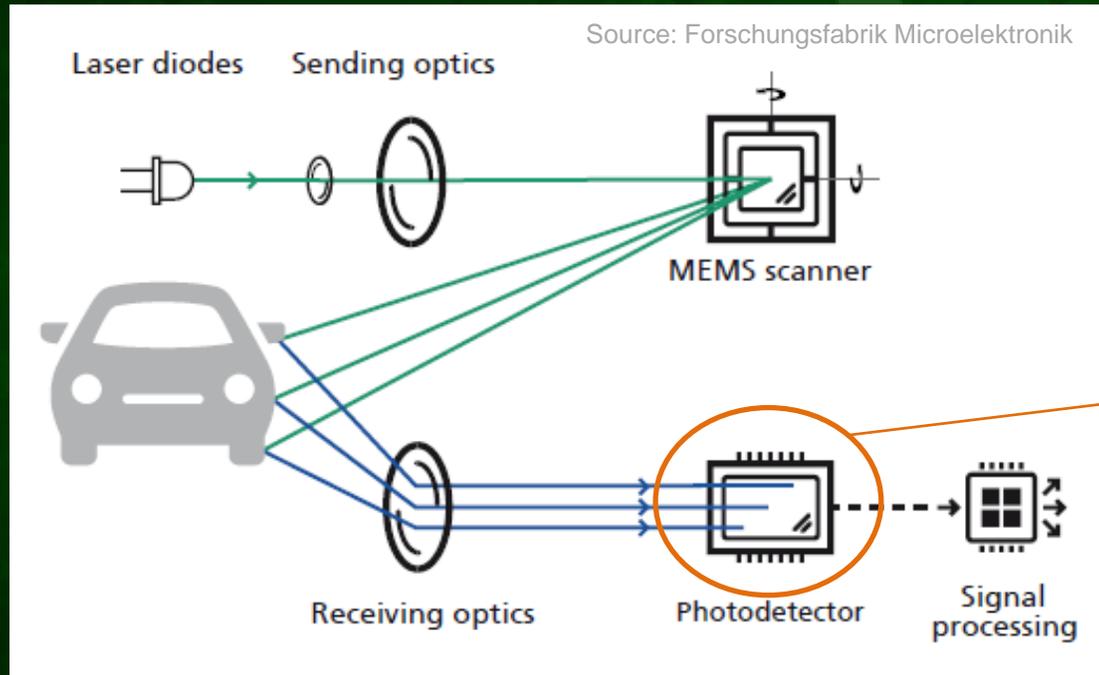
Imaging with LiDAR



2. Smart Probe Cards

Imaging with LiDAR

How to probe?



- **Photodetector with 1D/2D pixel array**
 - Stimulus of photodetector chip with *Illumination field module*

2. Illumination field module

Requirements (from customer test development)

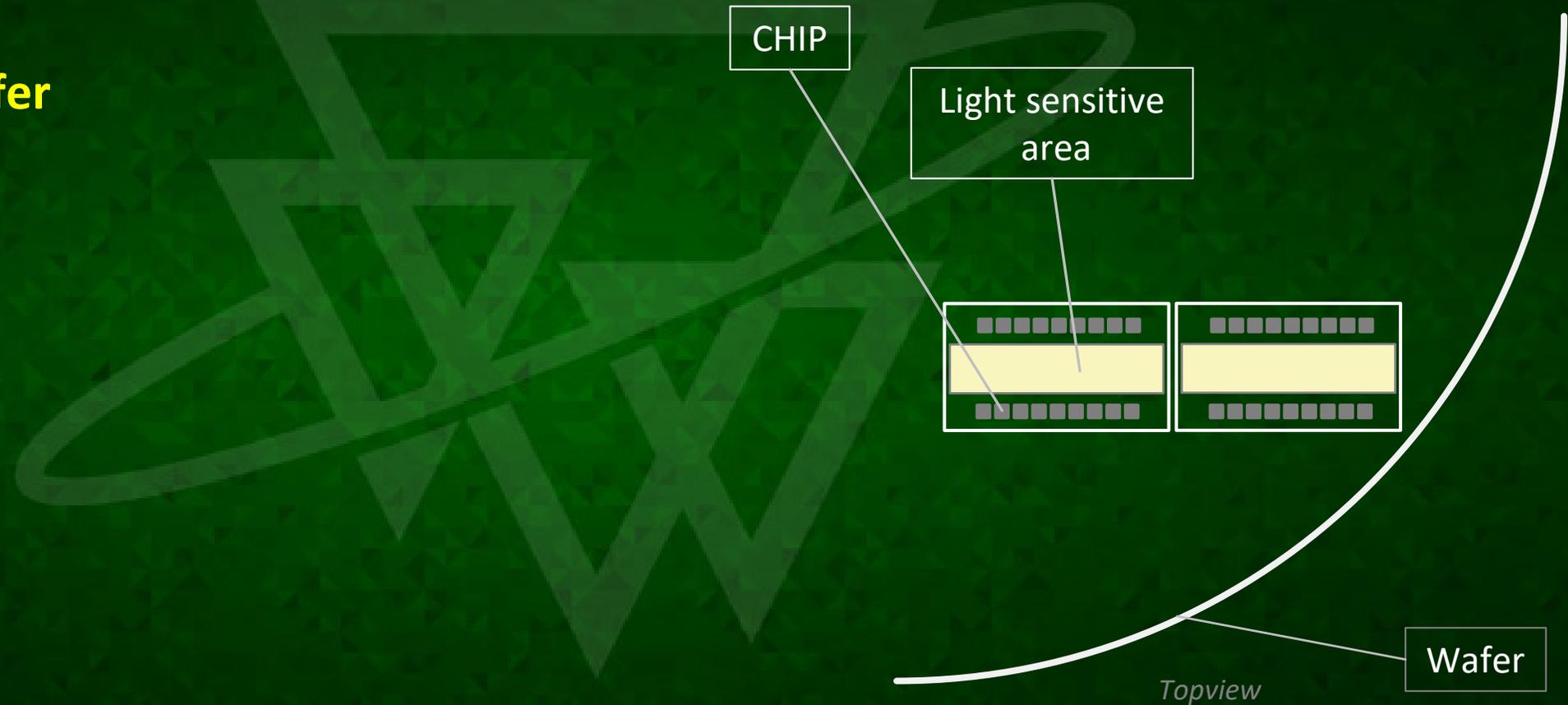
- Illuminated area in chip size scale
- High homogeneity of illuminated field: $\pm 2.5\%$
- Discrete intensity levels up to $10\text{W}/\text{m}^2$
- Narrow band illumination wave length
- Dual site measurement



2.1 Illumination field module

Design approach

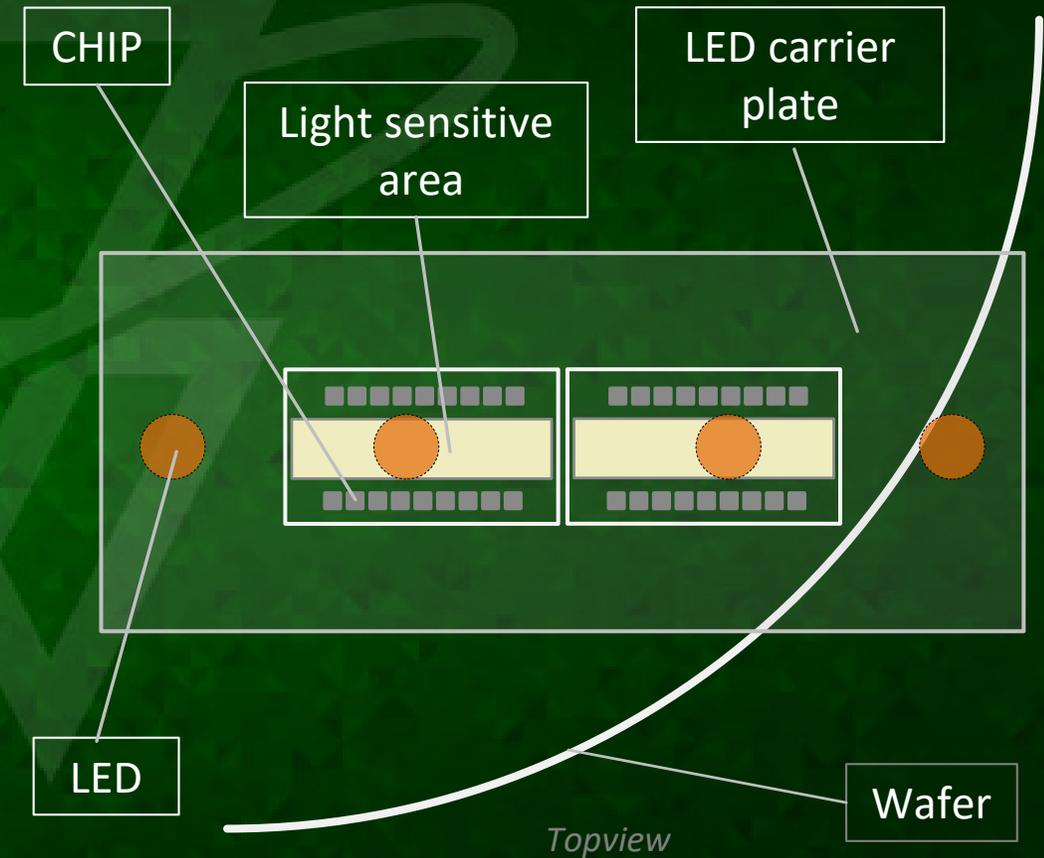
- **Situation on wafer**



2.1 Illumination field module

Design approach

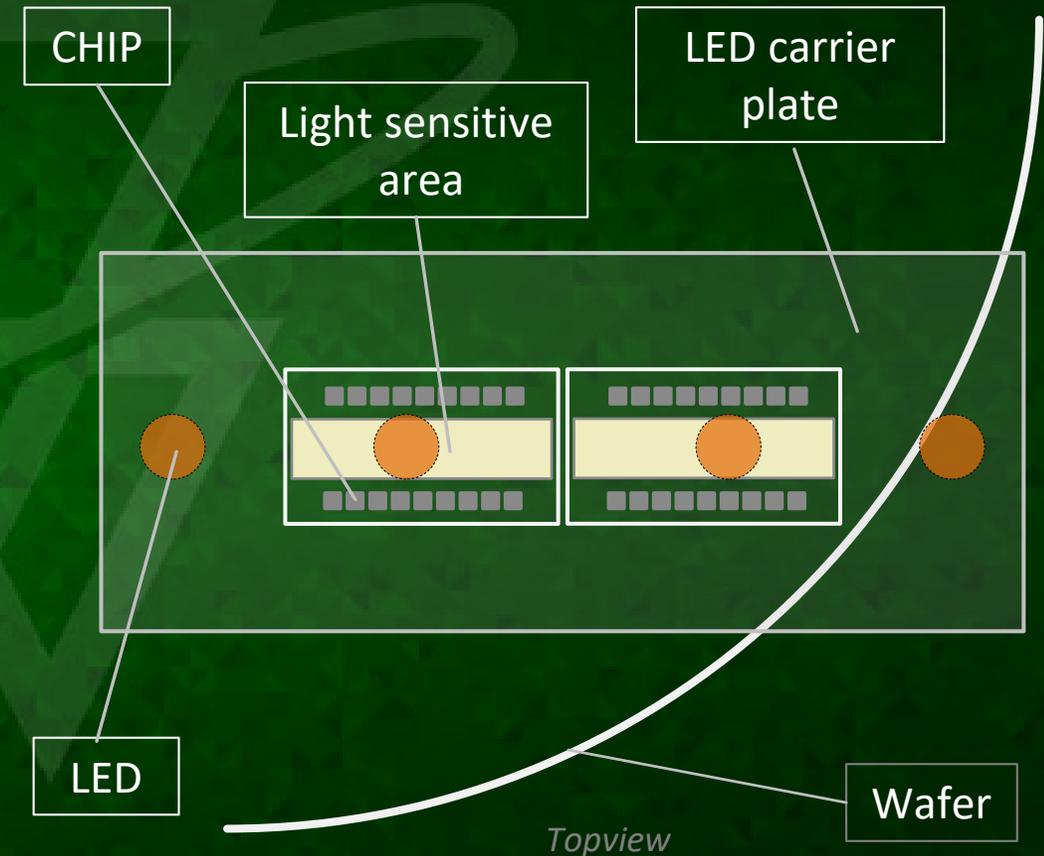
- **Situation on wafer**
- **1st Approach: 4 LEDs in line**



2.1 Illumination field module

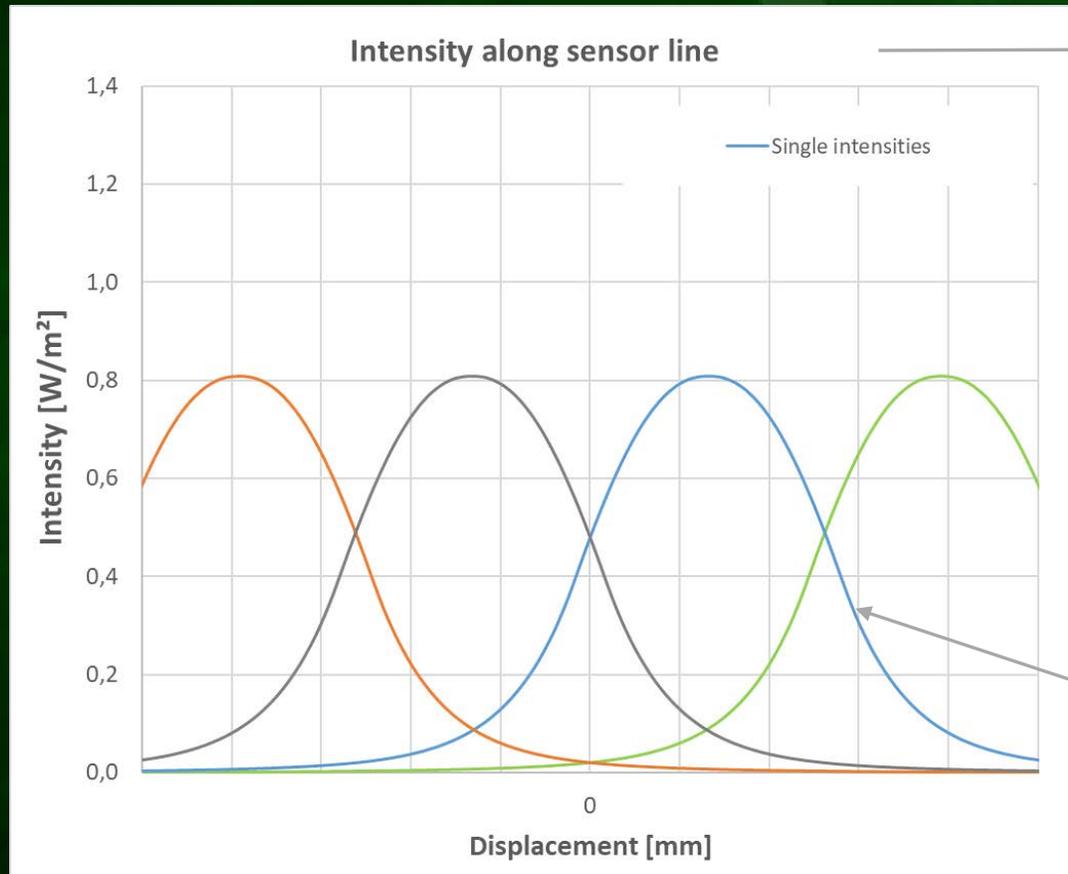
Design approach

- **Situation on wafer**
- **1st Approach: 4 LEDs in line**
- **Numerical simulation**
 - Light intensity along sensitive area on wafer
 - Intensity distribution of LED taken from datasheet
 - Iterative determination of ideal LED spacing

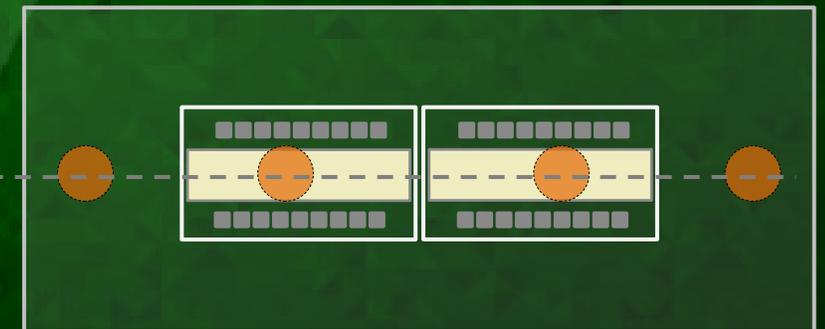


2.1 Illumination field module

Numerical simulation - Homogeneity



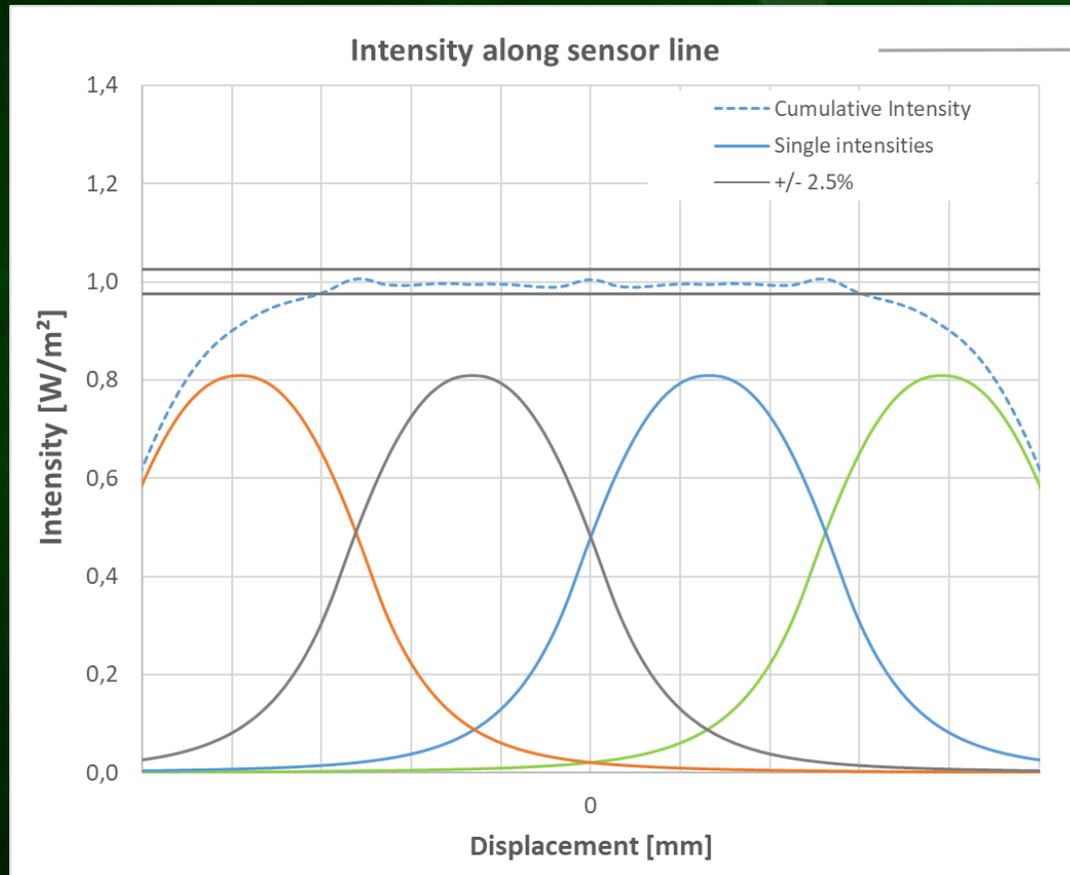
1st Approach: 4 LEDs in line



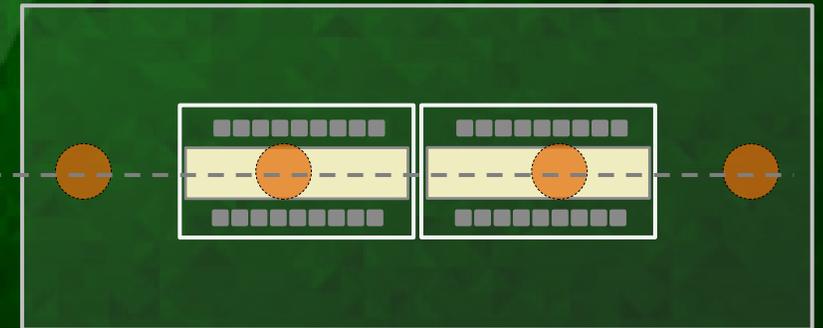
Intensity distribution from LED datasheet for specific distance

2.1 Illumination field module

Numerical simulation - Homogeneity

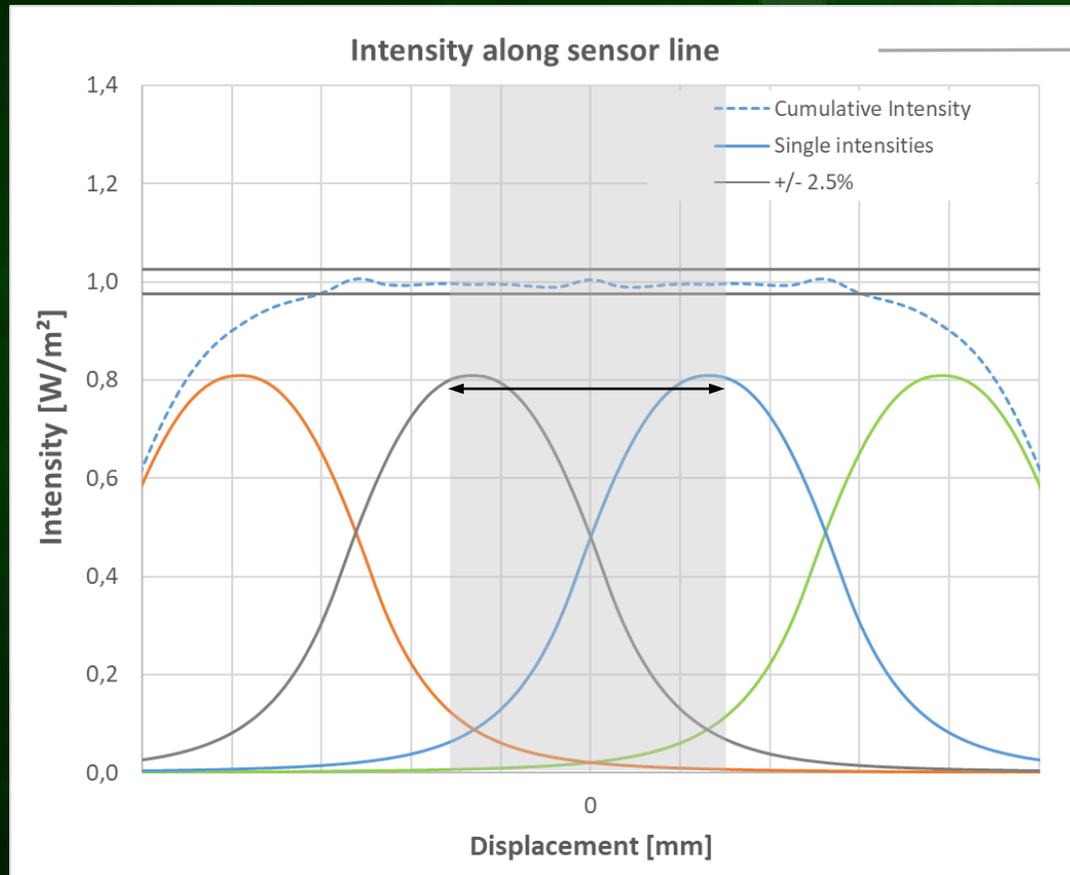


1st Approach: 4 LEDs in line

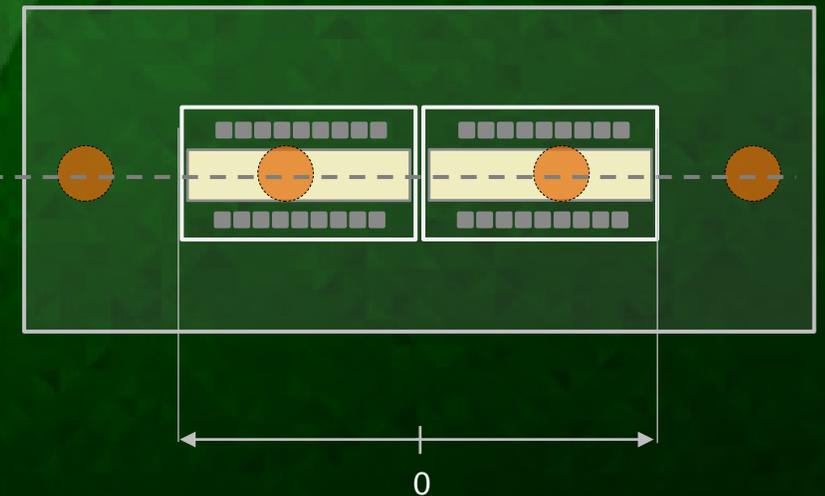


2.1 Illumination field module

Numerical simulation - Homogeneity

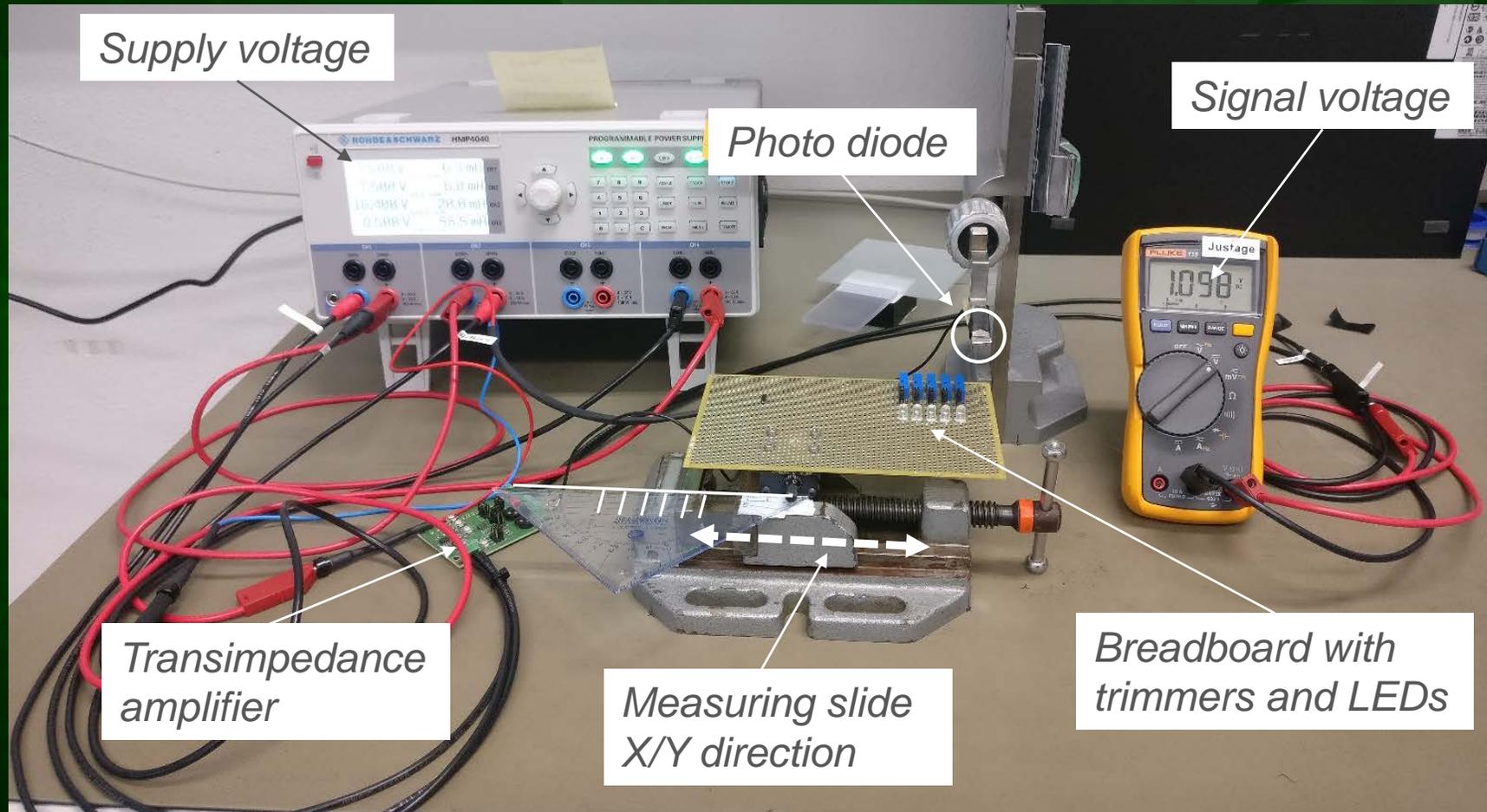


1st Approach: 4 LEDs in line



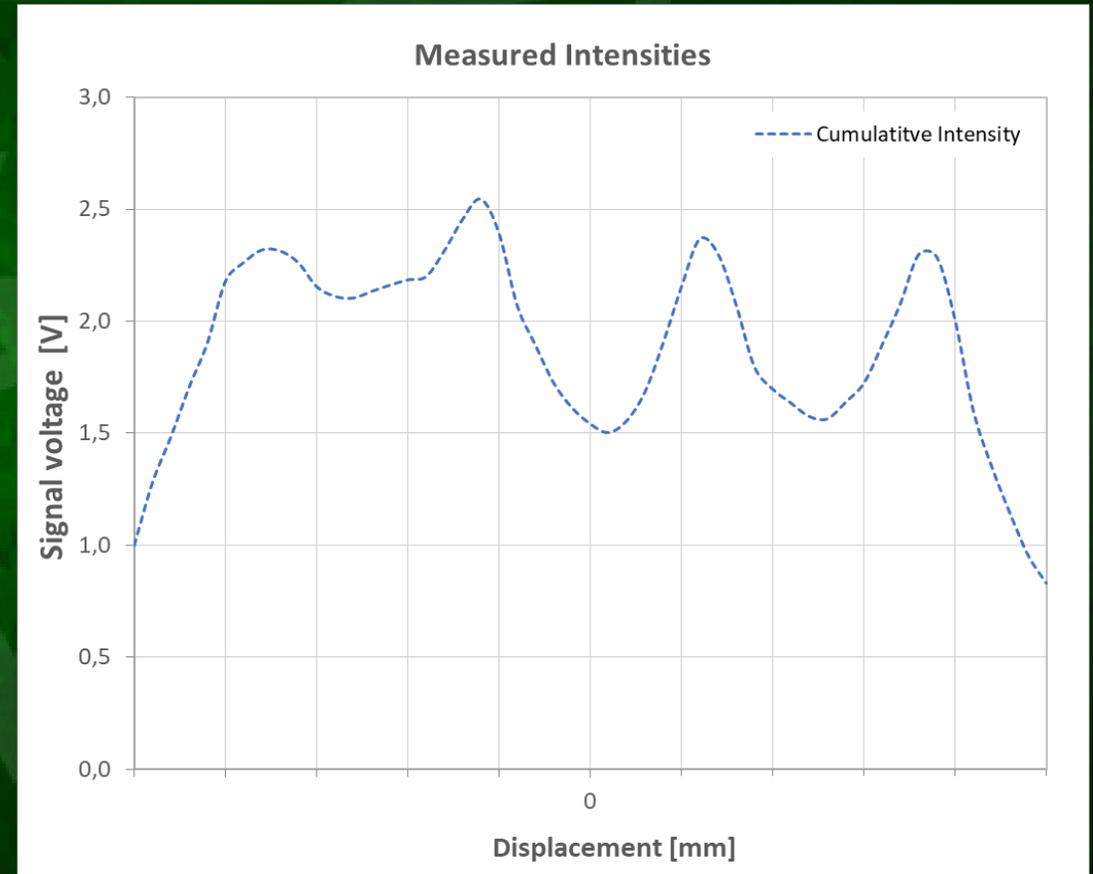
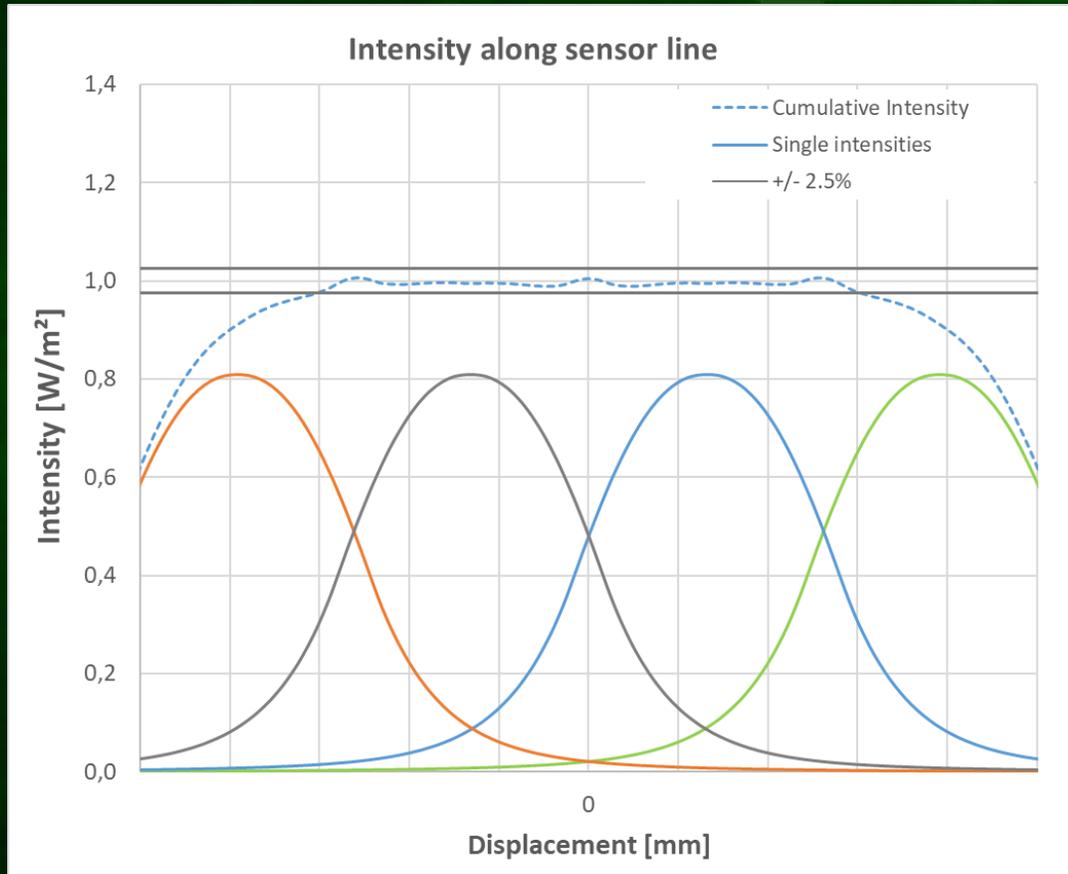
2.1 Illumination field module

Verification – First measurement setup



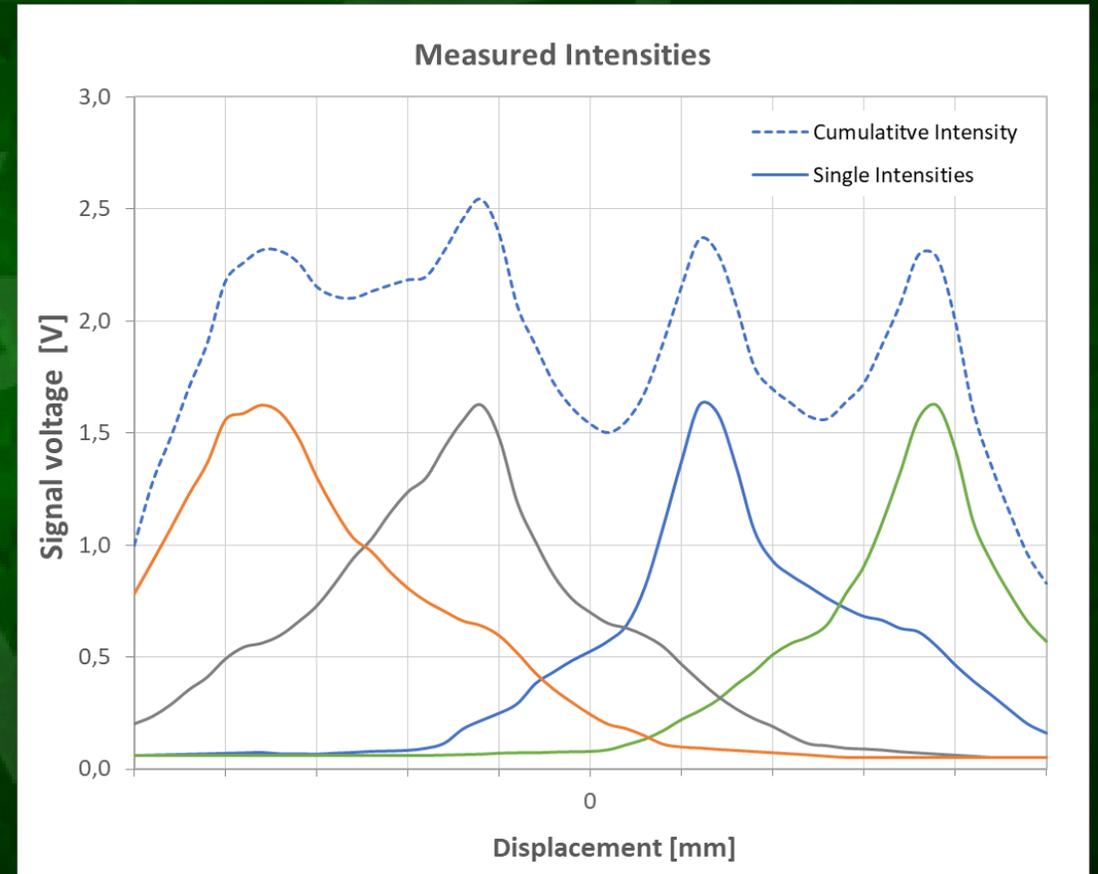
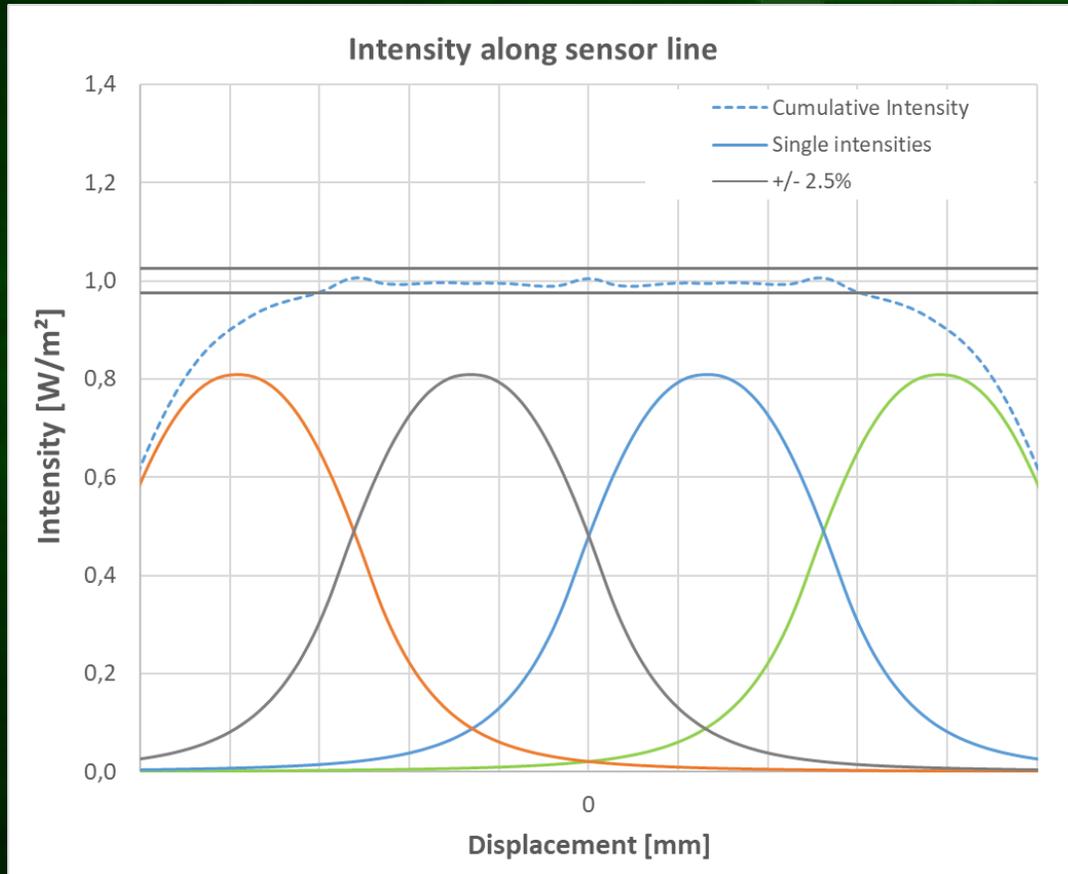
2.1 Illumination field module

Verification homogeneity – Simulation vs. measurement



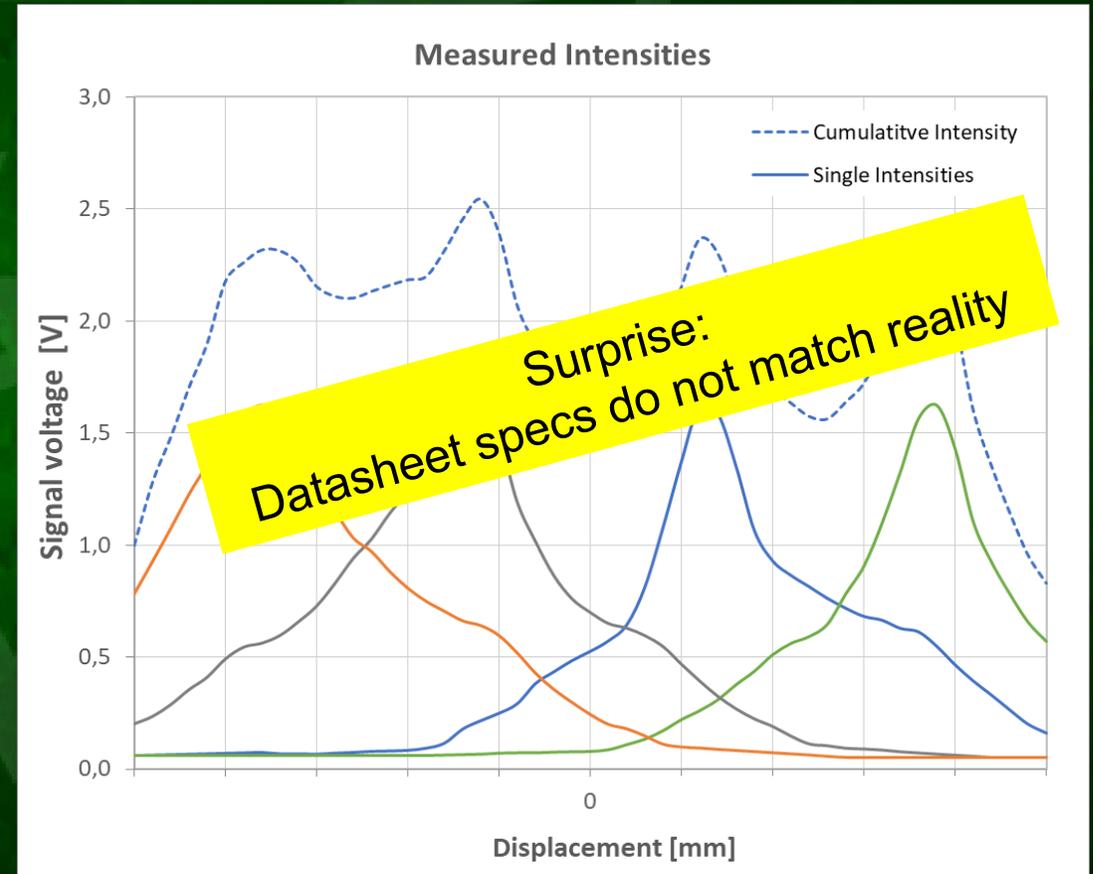
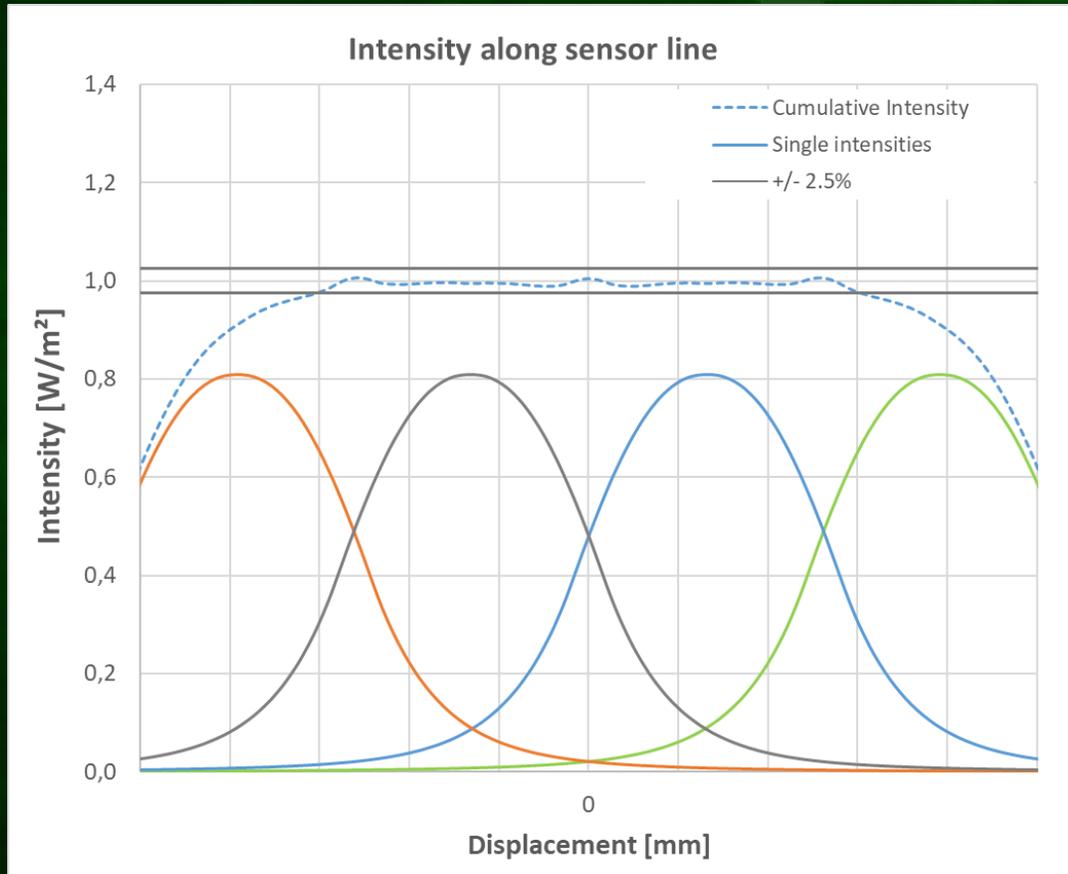
2.1 Illumination field module

Verification homogeneity – Simulation vs. measurement



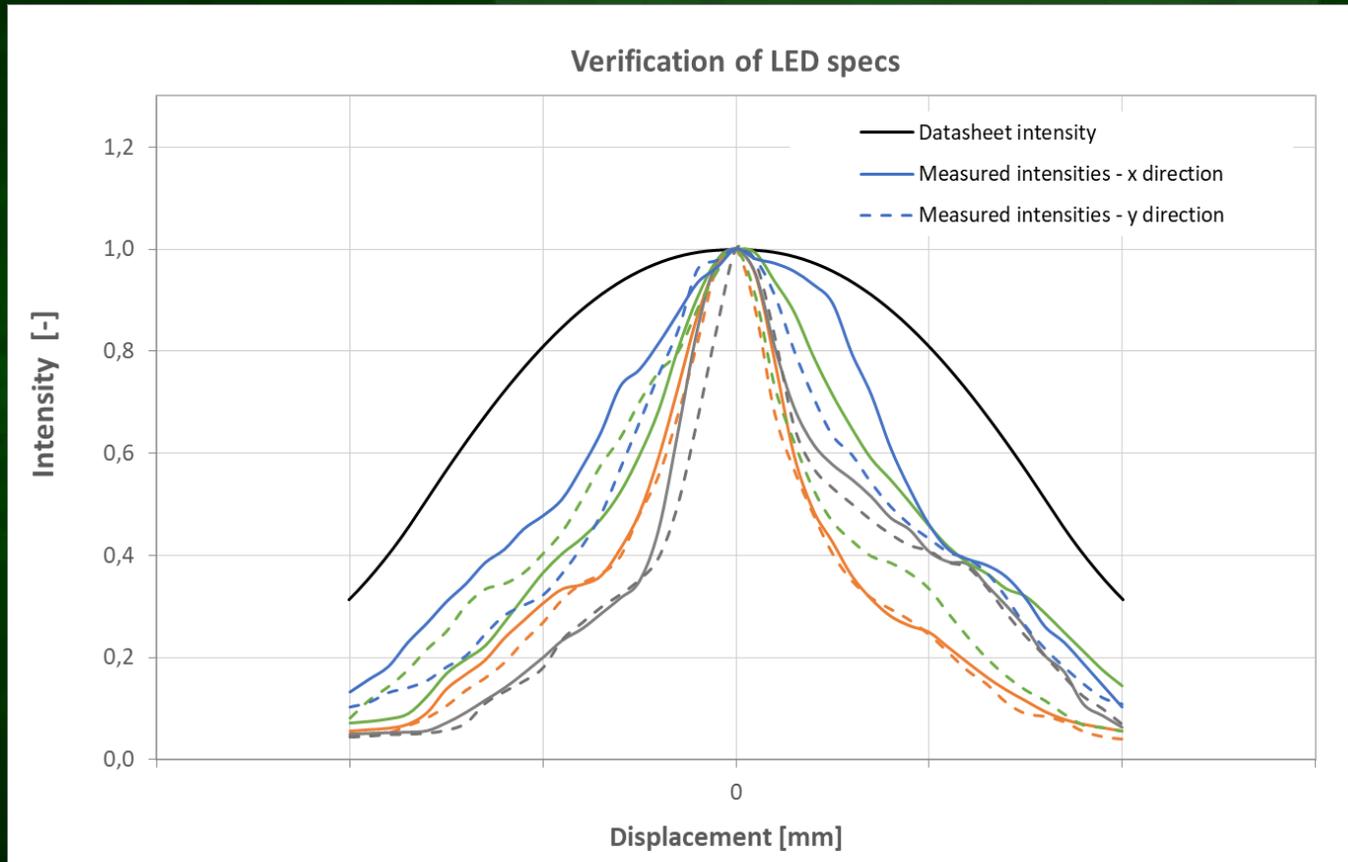
2.1 Illumination field module

Verification homogeneity – Simulation vs. measurement



2.1 Illumination field module

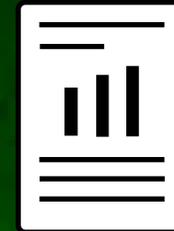
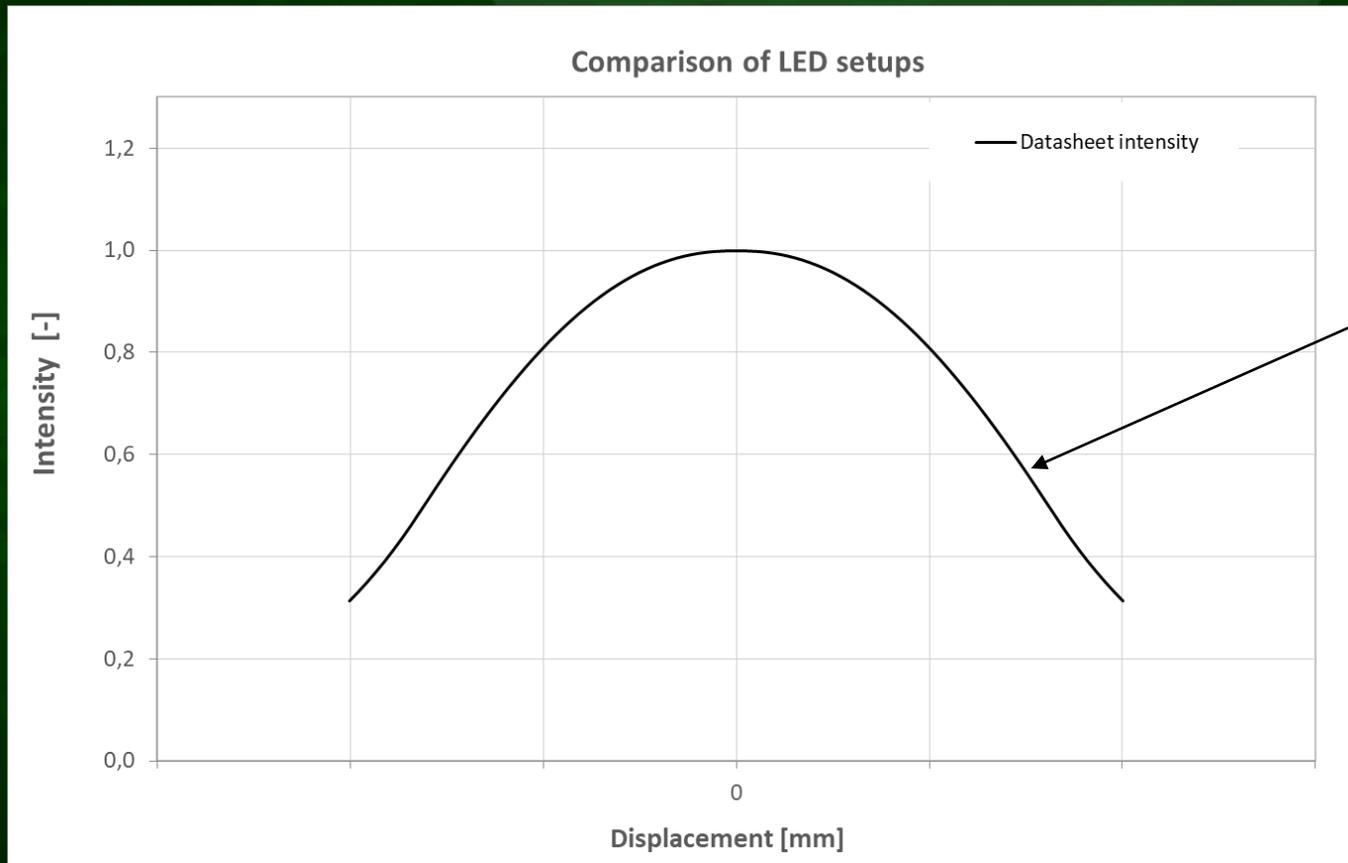
Verification homogeneity – Simulation vs. measurement



- Measured intensity of LED much more focused around axis than specified
- Significant variance between single LEDs

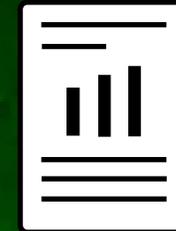
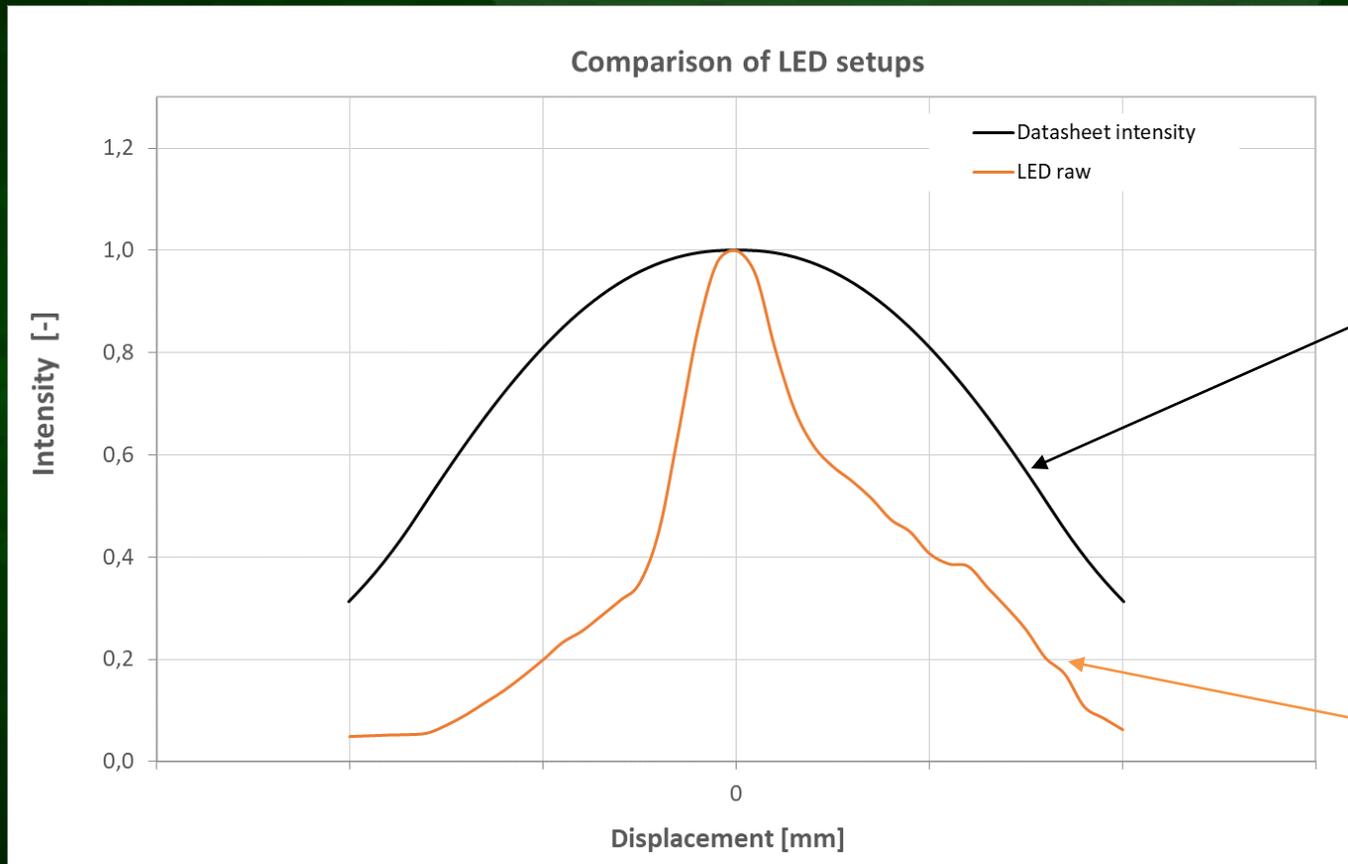
2.1 Illumination field module

Optimization of LED intensity distribution



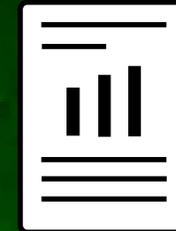
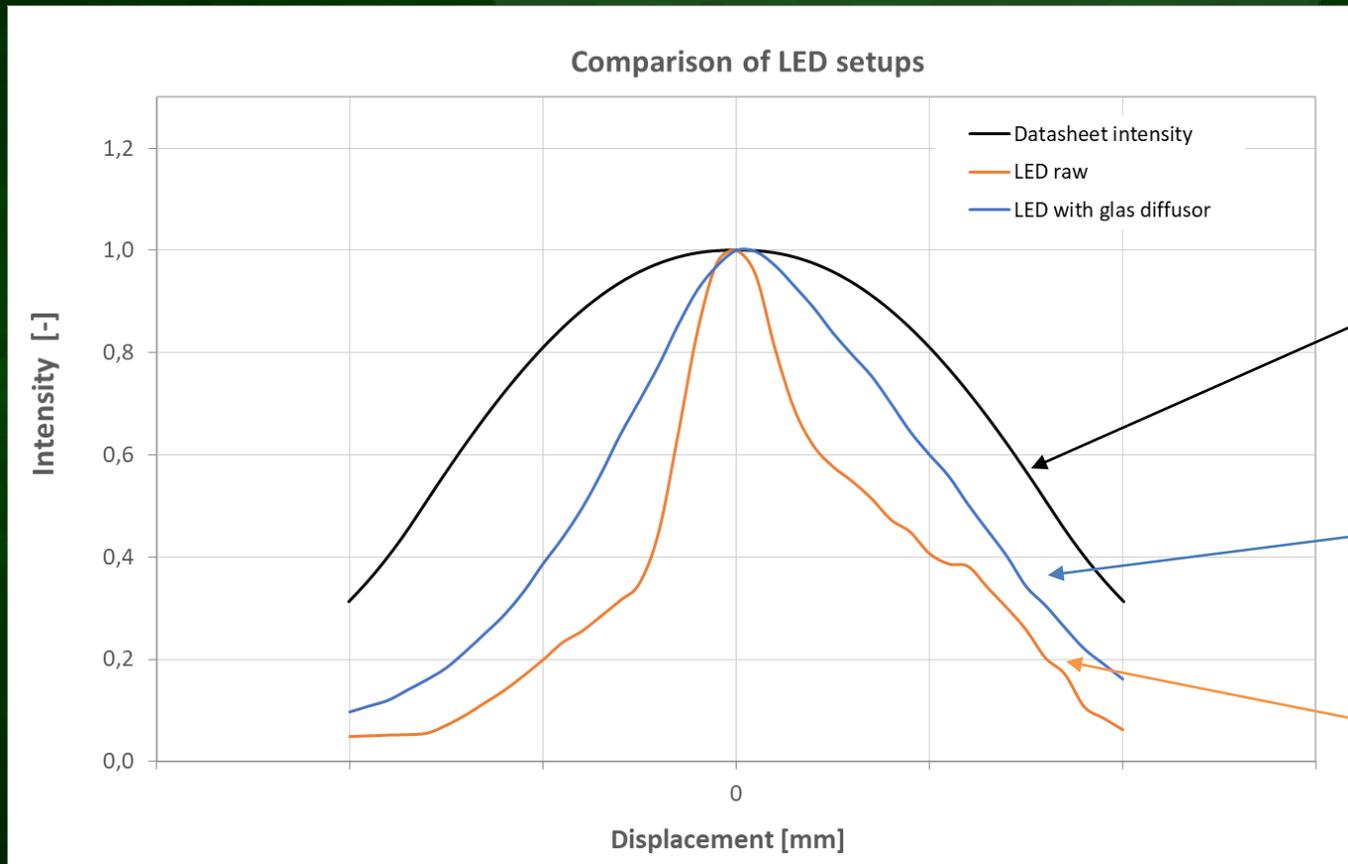
2.1 Illumination field module

Optimization of LED intensity distribution



2.1 Illumination field module

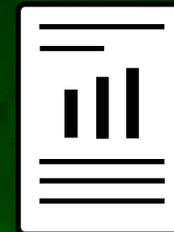
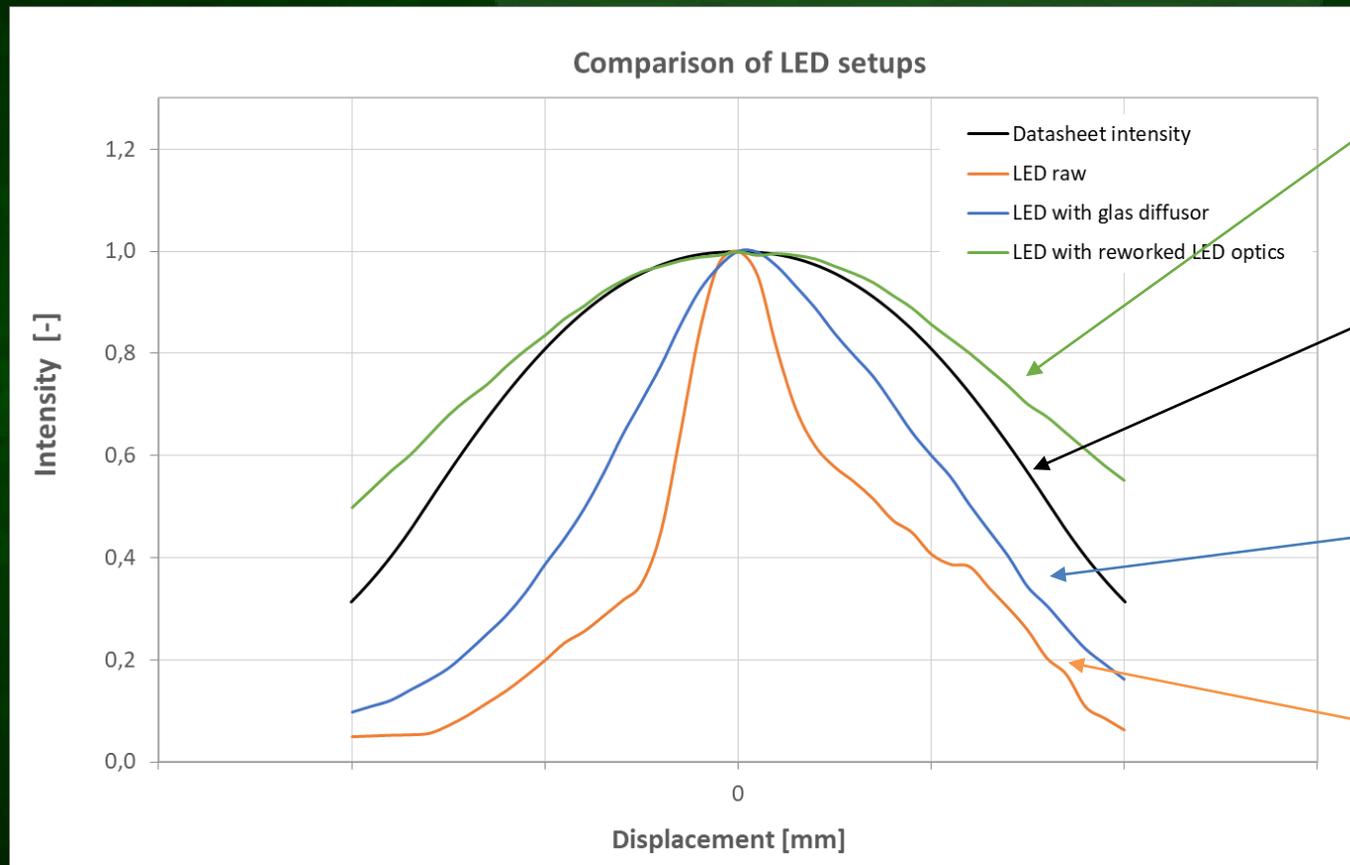
Optimization of LED intensity distribution



- Glass diffuser defocuses raw LED, but still asymmetric distribution

2.1 Illumination field module

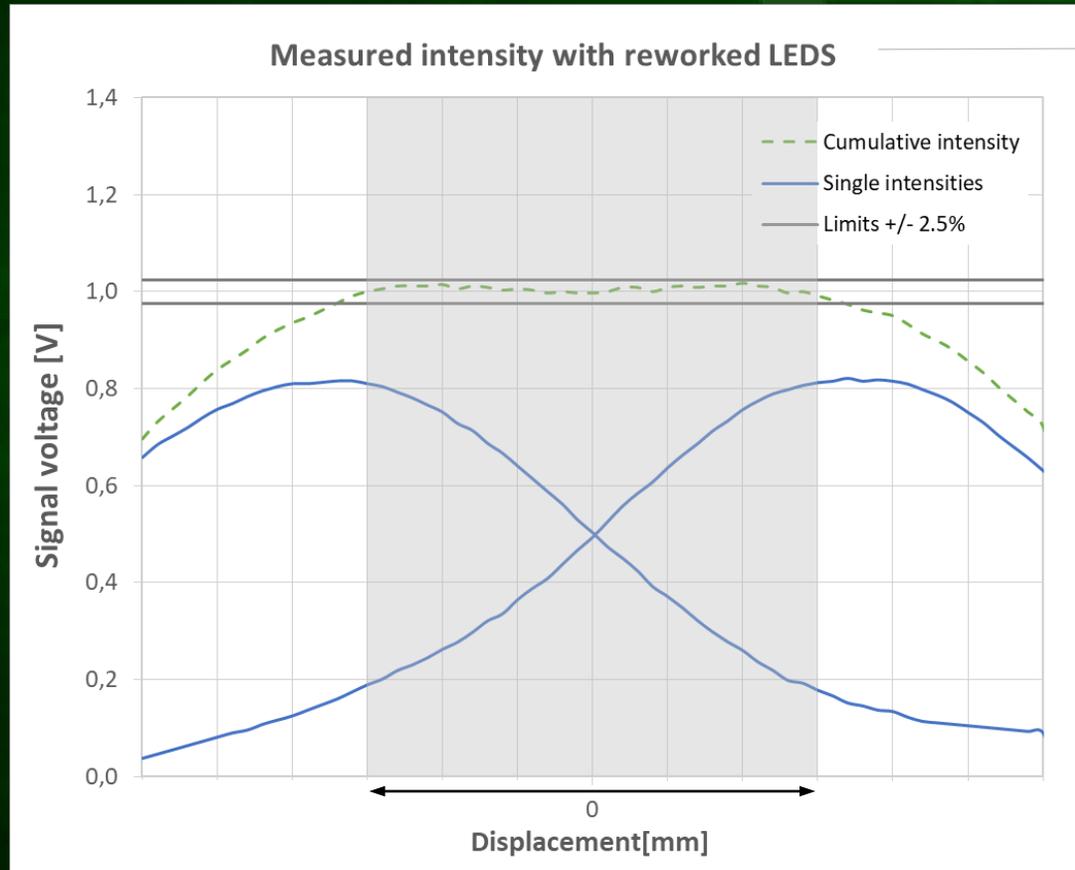
Optimization of LED intensity distribution



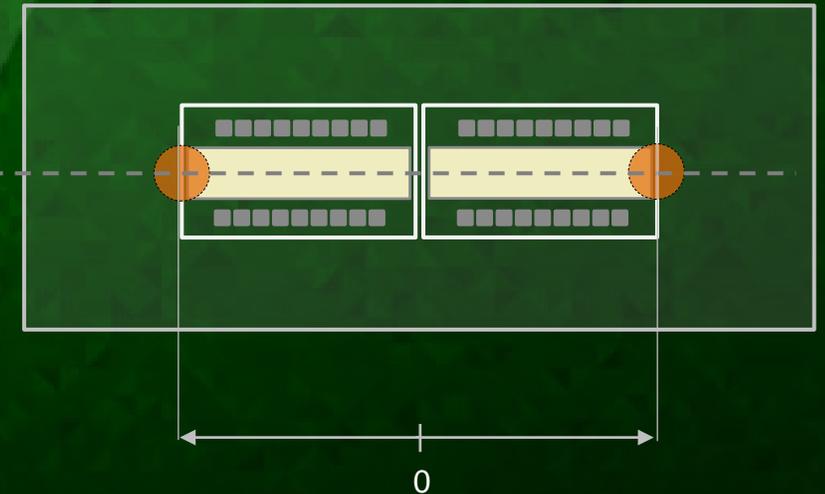
- Glass diffusor defocuses raw LED, but still asymmetric distribution
- Reworked LED optics leads to smoothed and symmetric distribution

2.1 Illumination field module

Optimization of LED intensity distribution



2nd Approach: 2 reworked LEDs in line

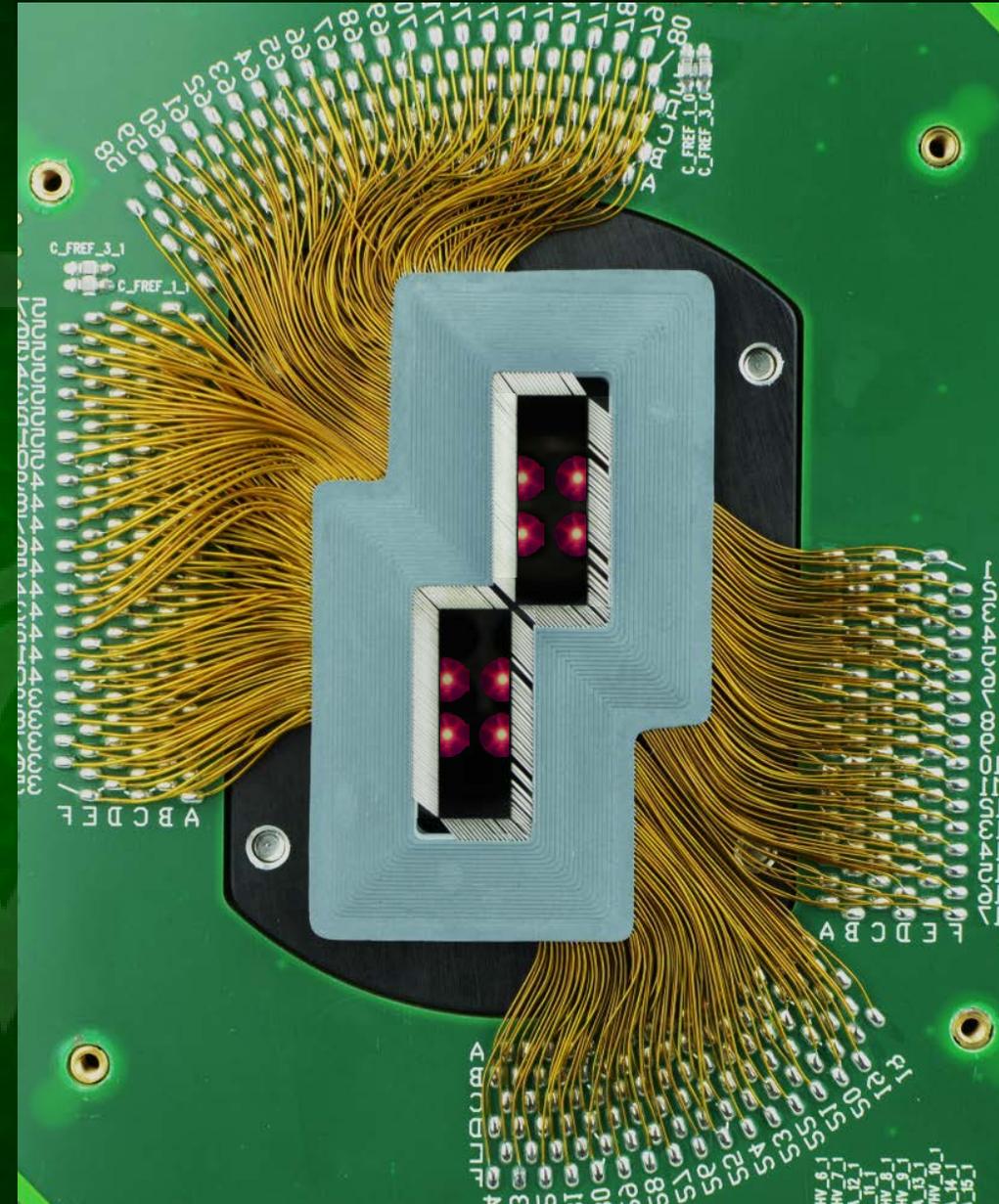


- Good results on the first try!

2.1 Illumination field module

Final concept

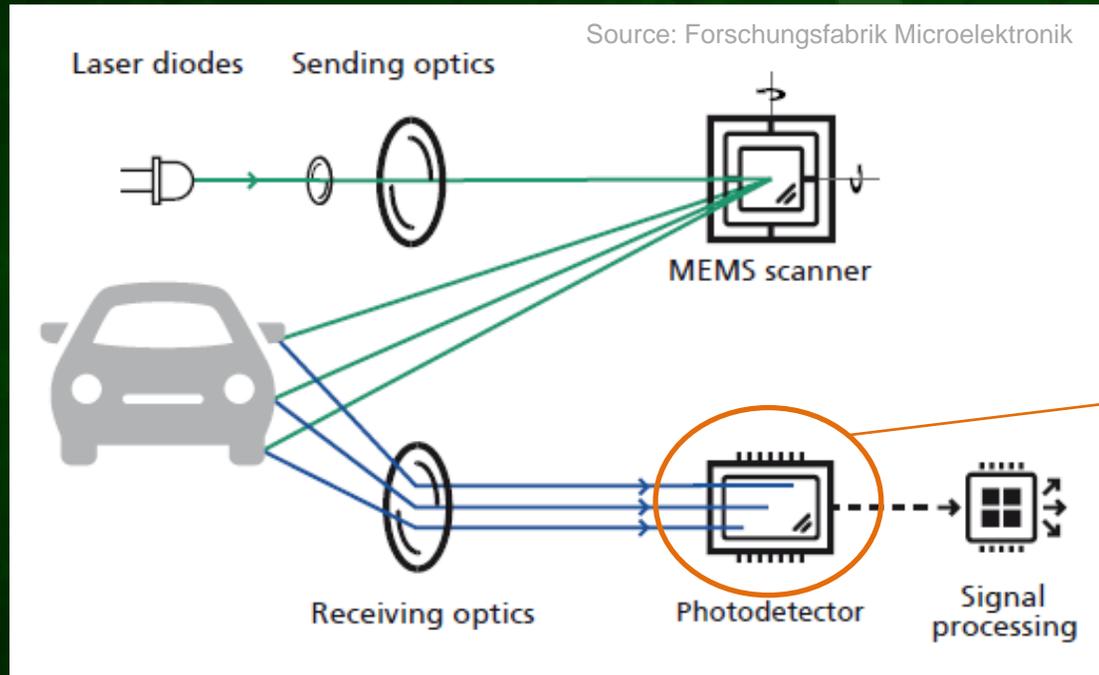
- **Usage of LEDs with reworked optics**
 - learned from shown approaches
- **Final concept needed some more changes and evolution steps**
 - 2x2 LED arrangement per site
 - Staggered multisite probing due to needle spider configuration
- **Temperature control applied**
- **Evaluation of long term stability of LEDs**
 - Life time test conducted over month



2. Smart Probe Cards

Imaging with LiDAR

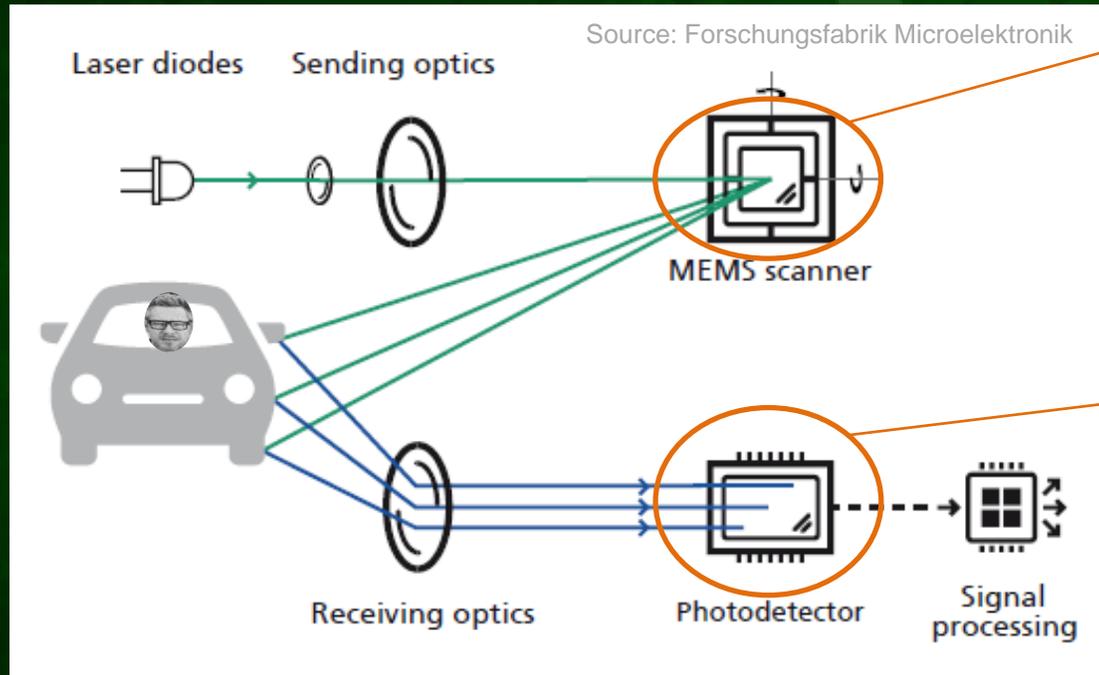
How to probe?



- **Photodetector with 1D/2D pixel array**
 - Stimulus of photodetector chip with *Illumination field module*

2. Smart Probe Cards

Imaging with LiDAR



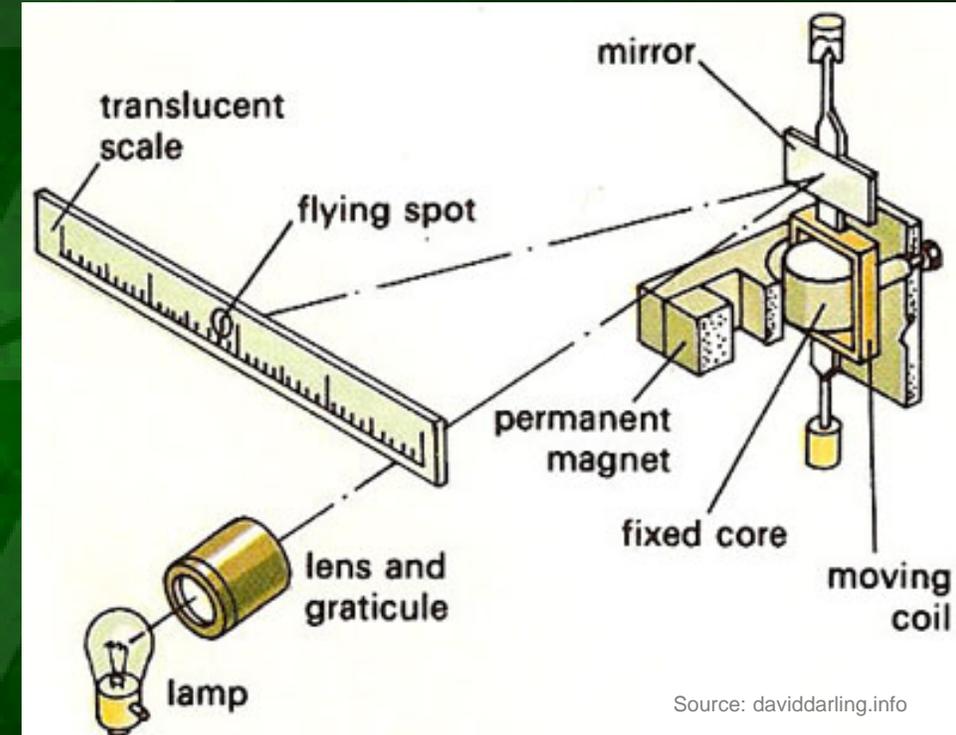
How to probe?

- **MEMS mirror**
 - Determination of tilt angle by use of a laser beam with *MEMS mirror module*
- **Photodetector with 1D/2D pixel array**
 - Stimulus of photodetector chip with *Illumination field module*

2.2 MEMS mirror module

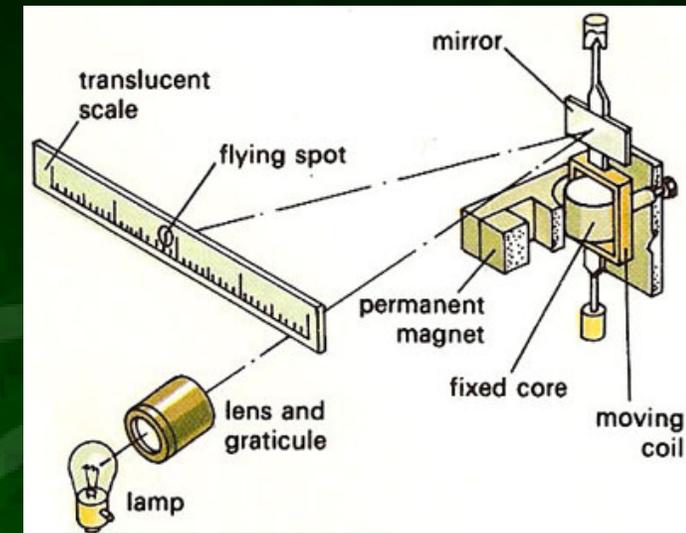
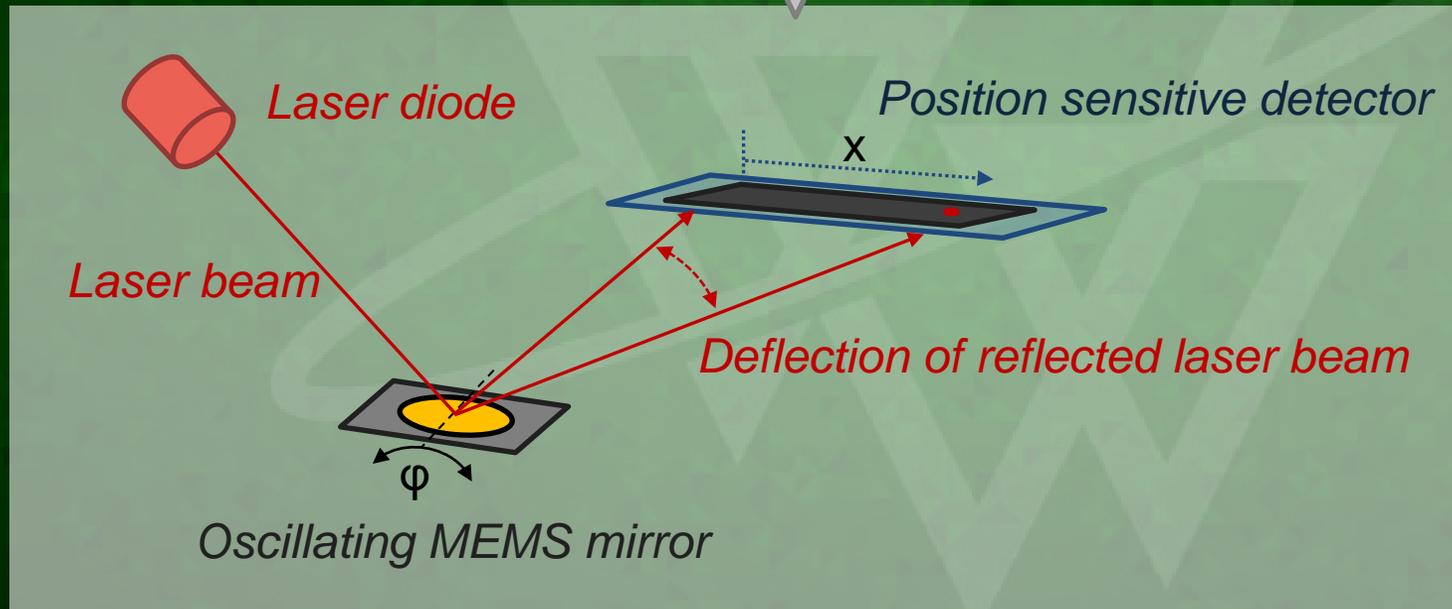
Requirements

- **Detection of tilt angle of MEMS mirror**
- **High angular accuracy**
- **Integration in probe card with vertical needle technology**
- **Measurement principle: Mirror galvanometer (1826)**
 - Usage of laser beam and Position Sensitive Detector



2.2 MEMS mirror module

Measurement principle



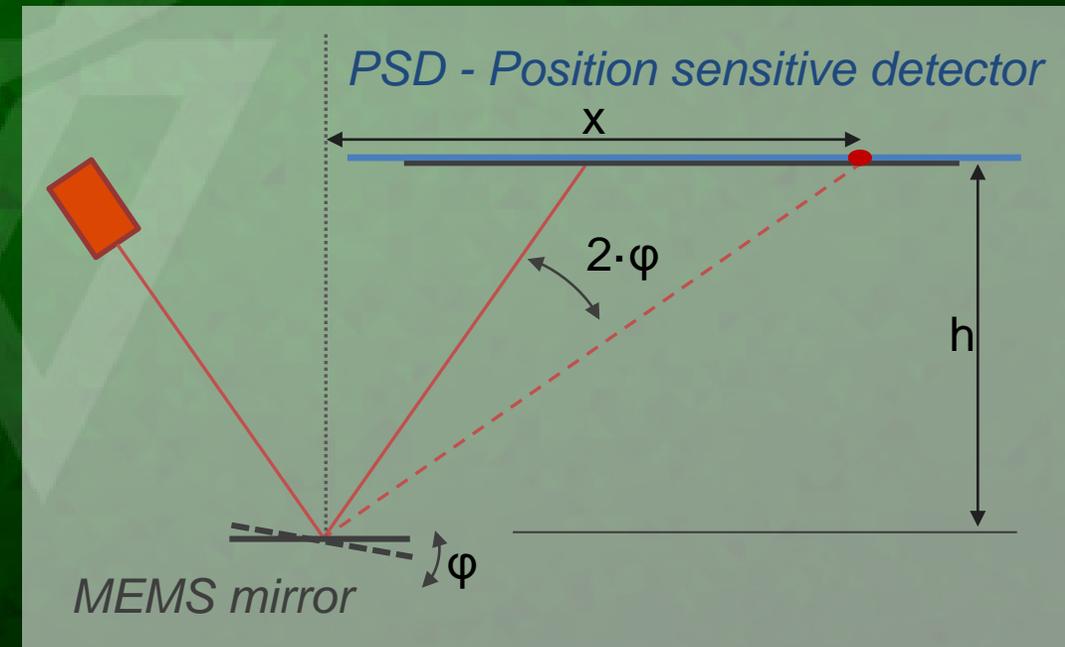
$$\varphi = f(x, \dots)$$

→ Mathematic correlation and measurement error calculation needed

2.2 MEMS mirror module

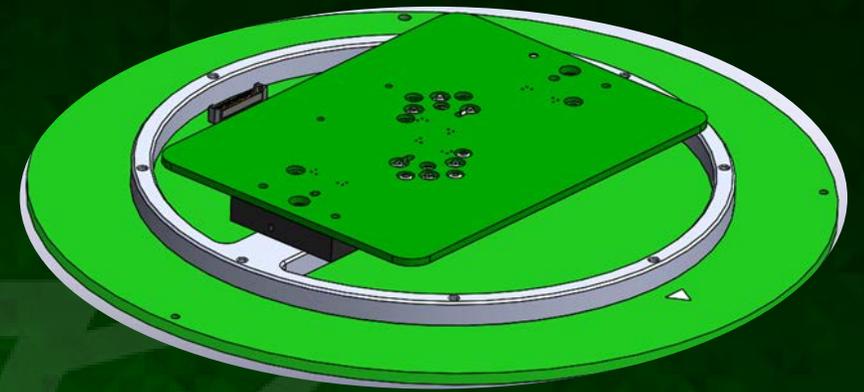
Measurement principle

- **A change of the mirror angle leads to a double change of the reflected beam angle (law of reflection)**
 - Very sensitive measurement principle
- **Mirror angle is a function of laser spot position x and distance h between MEMS mirror and PSD**
- **Distance error Δh_{error} leads to measurement error $\Delta \varphi_{\text{error}}$**
- **Consideration of**
 - Needle wear
 - Prober stage accuracy
 - PSD accuracy

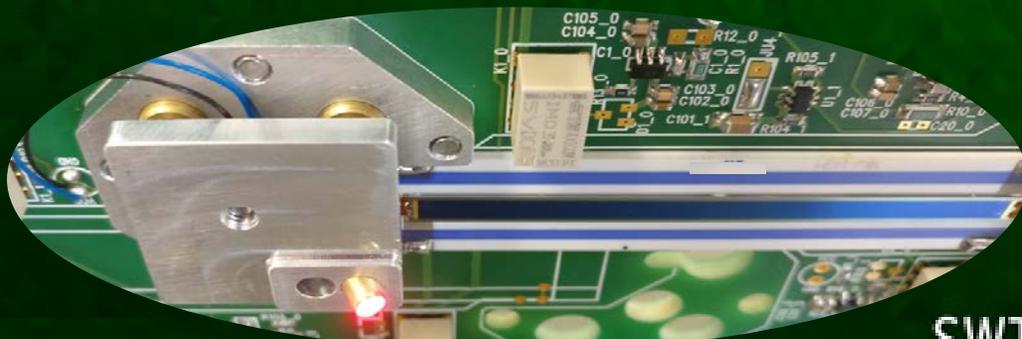
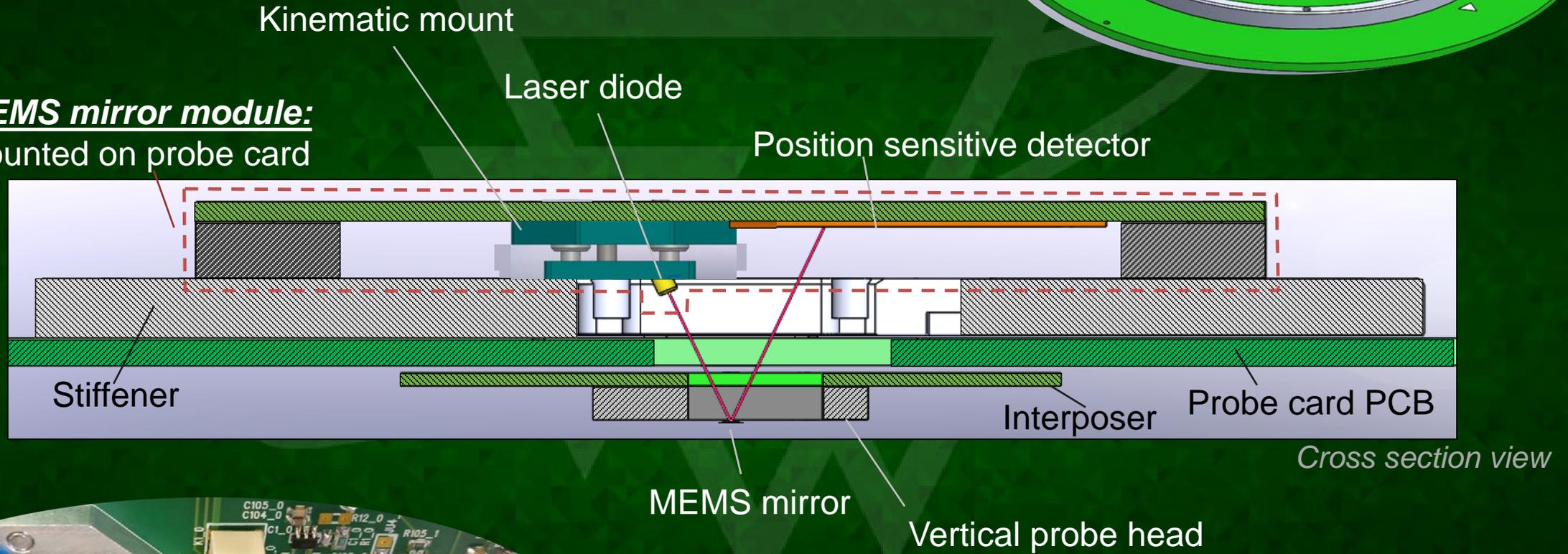


2.2 MEMS mirror module

Design

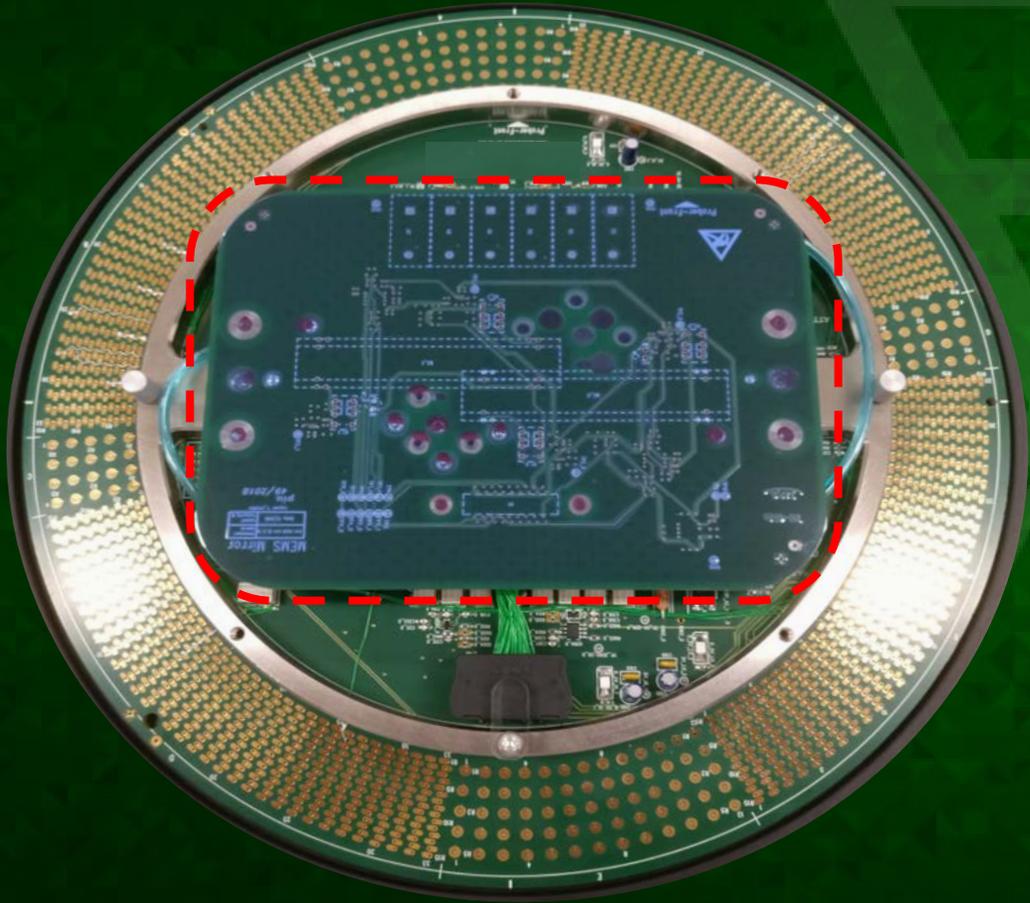


MEMS mirror module:
Mounted on probe card

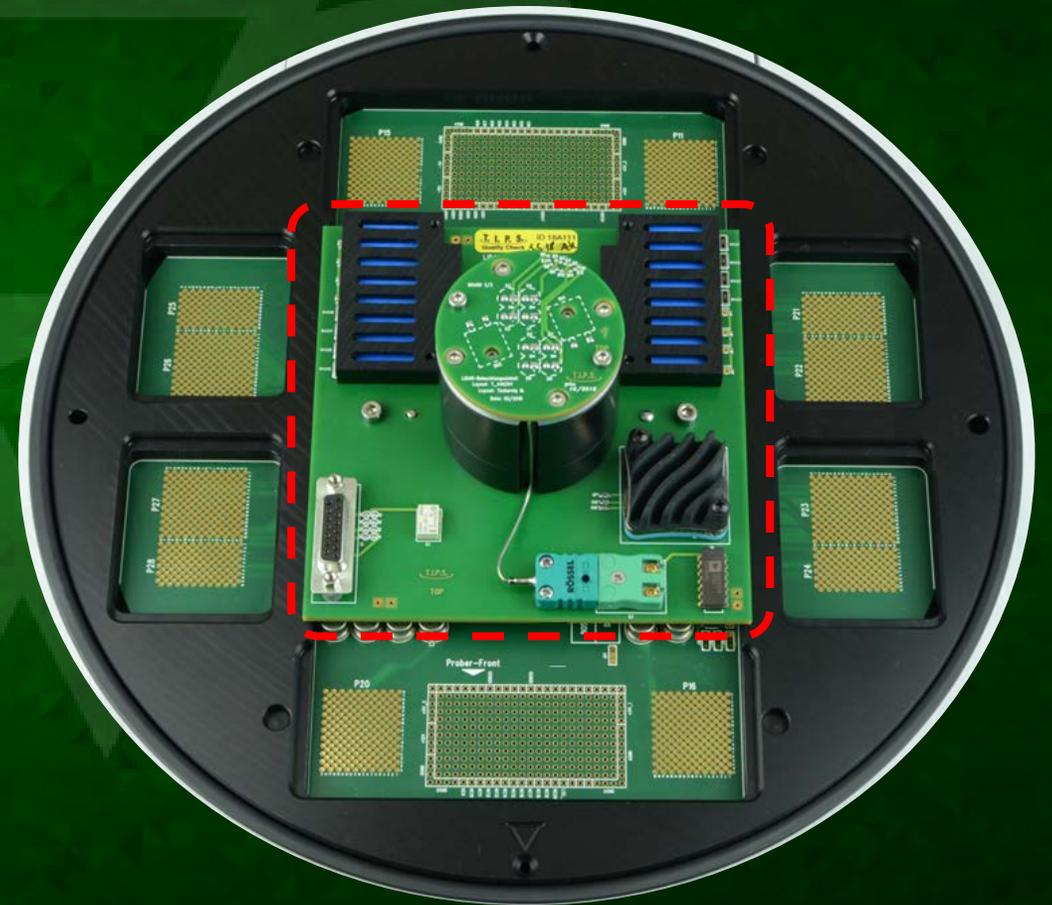


2. Smart Probe Cards

MEMS mirror module



Illumination field module



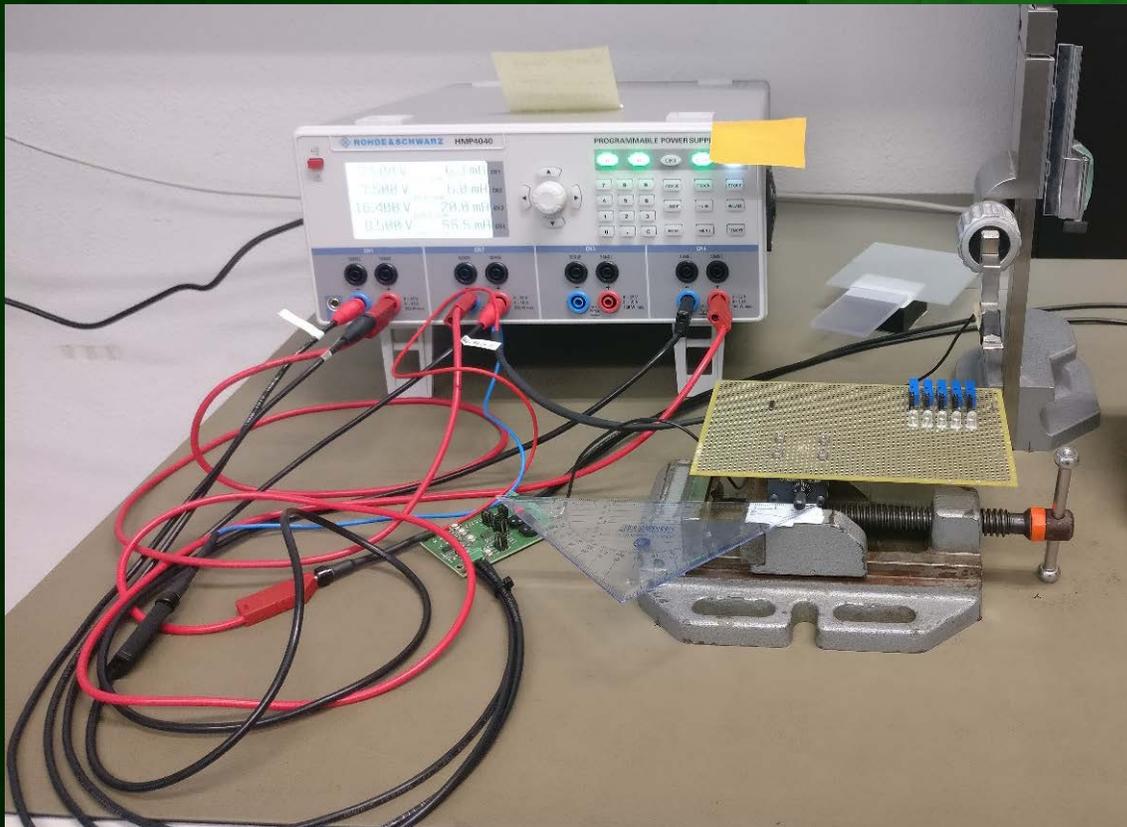
3. Conclusion

- **Development and integration of optical add-on modules for probe cards successful**
- **Added two more functional test technologies to our sensor test product portfolio**
 - Existing: Magnetic, pressure, gas atmospheres and light
 - New: Illumination field and MEMS mirror module
- **And..... never trust data sheets 😊**

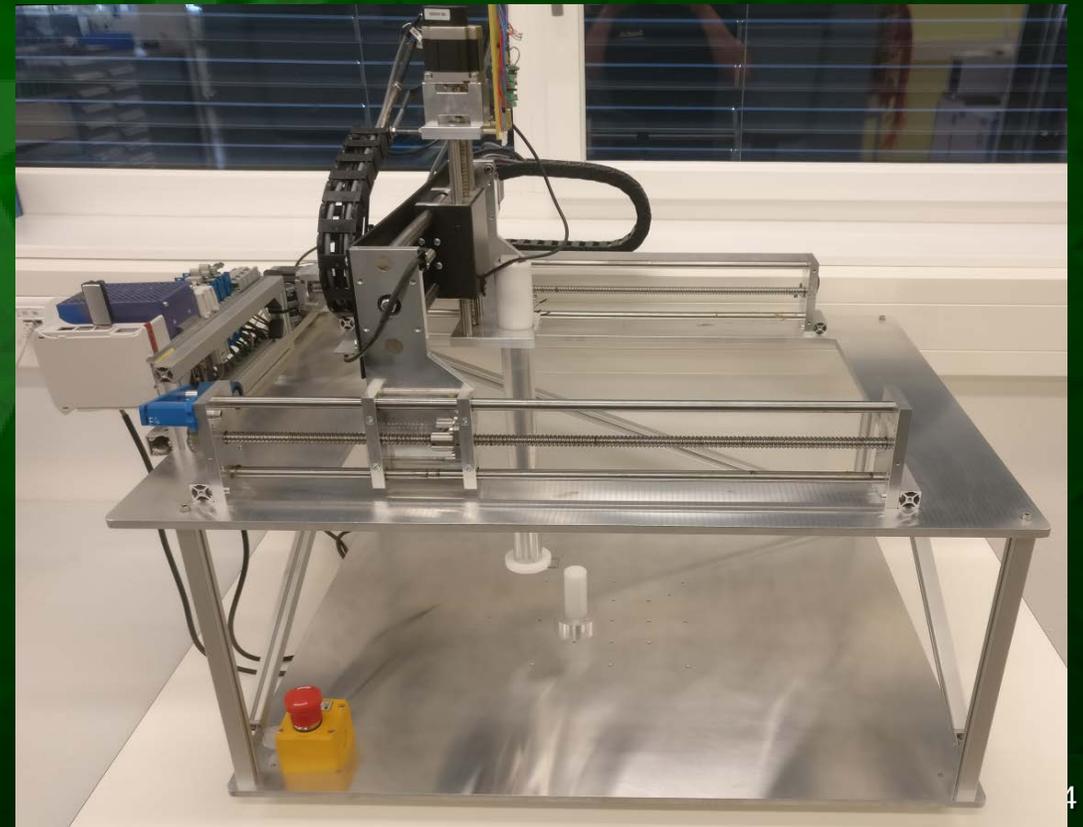
4. Acknowledgement

- Unnamed customers willing to realize these interesting projects with us
- Our design and manufacturing team at T.I.P.S.

First setup



3 axis scanning unit



Thank you for your attention!

**Smart Cars –
Smart Probe Cards**



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